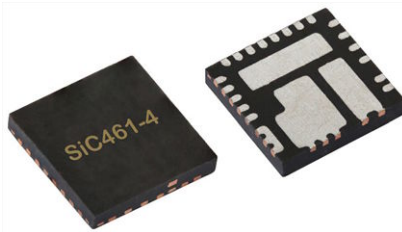


4.5 V to 60 V Input, 2 A, 4 A, 6 A, 10 A microBUCK® DC/DC Converter



LINKS TO ADDITIONAL RESOURCES



DESCRIPTION

The SiC46x is a family of wide input voltage, high efficiency synchronous buck regulators with integrated high side and low side power MOSFETs. Its power stage is capable of supplying high continuous current at up to 2 MHz switching frequency. This regulator produces an adjustable output voltage down to 0.8 V from 4.5 V to 60 V input rail to accommodate a variety of applications, including computing, consumer electronics, telecom, and industrial.

SiC46x's architecture allows for ultrafast transient response with minimum output capacitance and tight ripple regulation at very light load. The device enables loop stability regardless of the type of output capacitor used, including low ESR ceramic capacitors. The device also incorporates a power saving scheme that significantly increases light load efficiency. The regulator integrates a full protection feature set, including over current protection (OCP), output overvoltage protection (OVP), short circuit protection (SCP), output undervoltage protection (UVP) and over temperature protection (OTP). It also has UVLO for input rail and a user programmable soft start.

The SiC46x family is available in 2 A, 4 A, 6 A, 10 A pin compatible 5 mm by 5 mm lead (Pb)-free power enhanced MLP55-27L package.

TYPICAL APPLICATION CIRCUIT

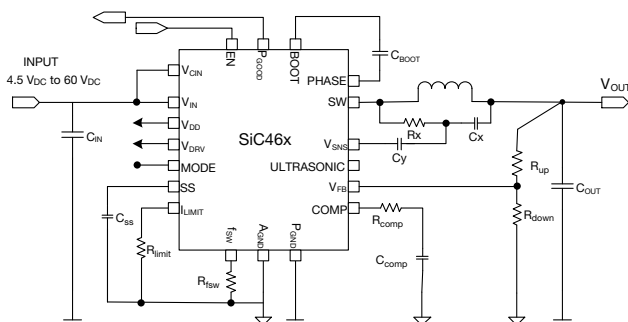


Fig. 1 - Typical Application Circuit for SiC46x

FEATURES

- Versatile
 - Single supply operation from 4.5 V to 60 V input voltage
 - Adjustable output voltage down to 0.8 V
 - Scalable solution 2 A (SiC464), 4 A (SiC463), 6 A (SiC462), 10 A (SiC461)
 - Output voltage tracking and sequencing with pre-bias start up
 - $\pm 1\%$ output voltage accuracy at $-40\text{ }^\circ\text{C}$ to $+125\text{ }^\circ\text{C}$
- Highly efficient
 - 98% peak efficiency
 - 4 μA supply current at shutdown
 - 235 μA operating current, not switching
- Highly configurable
 - Adjustable switching frequency from 100 kHz to 2 MHz
 - Adjustable soft start and adjustable current limit
 - 3 modes of operation, forced continuous conduction, power save or ultrasonic
- Robust and reliable
 - Output over voltage protection
 - Output under voltage / short circuit protection with auto retry
 - Power good flag and over temperature protection
 - Supported by Vishay PowerCAD online design simulation
- Material categorization: for definitions of compliance please see www.vishay.com/doc?99912



RoHS
COMPLIANT
HALOGEN
FREE

APPLICATIONS

- Industrial and automation
- Home automation
- Industrial and server computing
- Networking, telecom, and base station power supplies
- Unregulated wall transformer
- Robotics
- High end hobby electronics: remote control cars, planes, and drones
- Battery management systems
- Power tools
- Vending, ATM, and slot machines

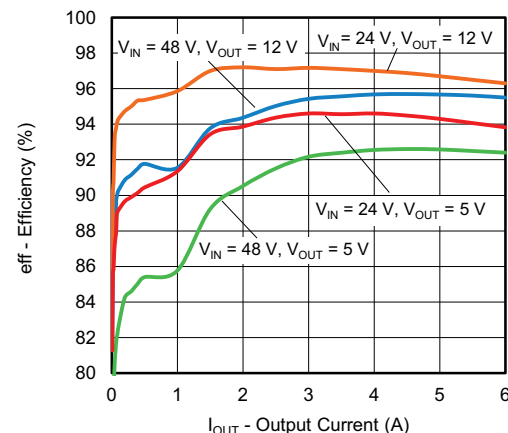
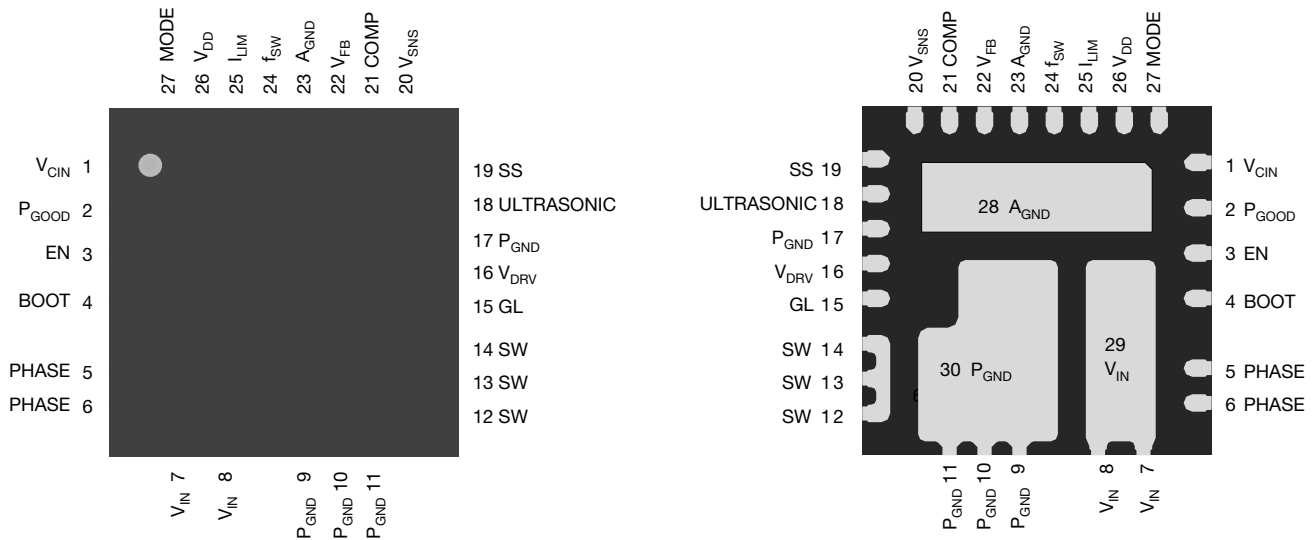


Fig. 2 - SiC462 Efficiency vs. Output Current

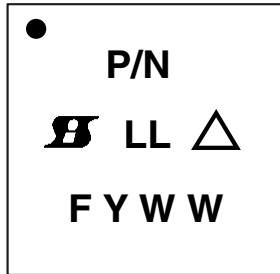
PIN CONFIGURATION

Fig. 3 - SiC46x Pin Configuration

| PIN DESCRIPTION | | |
|-------------------|-------------|---|
| PIN NUMBER | SYMBOL | DESCRIPTION |
| 1 | V_{CIN} | Supply voltage for internal regulators V_{DD} and V_{DRV} . This pin should be tied to V_{IN} , but can also be connected to a lower supply voltage ($> 5\text{ V}$) to reduce losses in the internal linear regulators |
| 2 | P_{GOOD} | Open-drain power good indicator - high impedance indicates power is good. An external pull-up resistor is required |
| 3 | EN | Enable pin. Tie high/low to enable/disable the IC accordingly. This is a high voltage compatible pin, can be tied to 60 V |
| 4 | BOOT | High side driver bootstrap voltage |
| 5, 6 | PHASE | Return path of high side gate driver |
| 7, 8, 29 | V_{IN} | Power stage input voltage. Drain of high side MOSFET |
| 9, 10, 11, 17, 30 | P_{GND} | Power ground |
| 12, 13, 14 | SW | Power stage switch node |
| 15 | GL | Low side MOSFET gate signal |
| 16 | V_{DRV} | Supply voltage for internal gate driver. When using the internal LDO as a bias power supply, V_{DRV} is the LDO output. Connect a $4.7\ \mu\text{F}$ decoupling capacitor to P_{GND} |
| 18 | ULTRASONIC | Float to disable ultrasonic mode, connect to V_{DD} to enable. Depending on the operation mode set by the mode pin, power save mode or forced continuous mode will be enabled when the ultrasonic mode is disabled |
| 19 | SS | Set the soft start ramp by connecting a capacitor to A_{GND} . An internal current source will charge the capacitor |
| 20 | V_{SNS} | Power inductor signal feedback pin for system stability compensation |
| 21 | COMP | Output of the internal error amplifier. The feedback loop compensation network is connected from this pin to the A_{GND} pin |
| 22 | V_{FB} | Feedback input for switching regulator used to program the output voltage - connect to an external resistor divider from V_{OUT} to A_{GND} |
| 23, 28 | A_{GND} | Analog ground |
| 24 | f_{SW} | Set the on-time by connecting a resistor to A_{GND} |
| 25 | I_{LIMIT} | Set the current limit by connecting a resistor to A_{GND} |
| 26 | V_{DD} | Bias supply for the IC. V_{DD} is an LDO output, connect a $1\ \mu\text{F}$ decoupling capacitor to A_{GND} |
| 27 | MODE | Set various operation modes by connecting a resistor to A_{GND} . See specification table for details |



| ORDERING INFORMATION | | |
|----------------------|---------------------|--------------|
| PART NUMBER | PACKAGE | MARKING CODE |
| SiC461ED-T1-GE3 | PowerPAK® MLP55-27L | SiC461 |
| SiC461EVB | Reference board | |
| SiC462ED-T1-GE3 | PowerPAK® MLP55-27L | SiC462 |
| SiC462EVB | Reference board | |
| SiC463ED-T1-GE3 | PowerPAK® MLP55-27L | SiC463 |
| SiC463EVB | Reference board | |
| SiC464ED-T1-GE3 | PowerPAK® MLP55-27L | SiC464 |
| SiC464EVB | Reference board | |

PART MARKING INFORMATION



- = pin 1 indicator
- P/N = part number code
- = Siliconix logo
- = ESD symbol
- F = assembly factory code
- Y = year code
- WW = week code
- LL = lot code

| ABSOLUTE MAXIMUM RATINGS (T _A = 25 °C, unless otherwise noted) | | | |
|---|--|---|------|
| ELECTRICAL PARAMETER | CONDITIONS | LIMITS | UNIT |
| V _{CIN} , V _{IN} | Reference to P _{GND} | -0.3 to 66 | V |
| EN | Reference to A _{GND} | -0.3 to 60 | |
| SW / PHASE | Reference to P _{GND} | -0.3 to 66 | |
| V _{DRV} | Reference to P _{GND} | -0.3 to 6 | |
| V _{DD} | Reference to A _{GND} | -0.3 to 6 | |
| SW / PHASE (AC) | Reference to P _{GND} ; 100 ns | -10 to 72 | |
| BOOT | | -0.3 to V _{PHASE} + V _{DRV} | |
| A _{GND} to P _{GND} | | -0.3 to 0.3 | |
| All other pins | Reference to A _{GND} | -0.3 to V _{DD} + 0.3 | |
| Temperature | | | |
| Junction temperature | T _J | -40 to +150 | °C |
| Storage temperature | T _{STG} | -65 to +150 | |
| Power Dissipation | | | |
| Thermal resistance from junction-to-ambient | | 12 | °C/W |
| Thermal resistance from junction-to-case | | 2 | |
| ESD Protection | | | |
| Electrostatic discharge protection | Human body model, JESD22-A114 | 2000 | V |
| | Charged device model, JESD22-A101 | 500 | |

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating/conditions for extended periods may affect device reliability.



| RECOMMENDED OPERATING CONDITIONS (all voltages referenced to GND = 0 V) | | | | |
|--|-------------|------|----------------------|------|
| PARAMETER | MIN. | TYP. | MAX. | UNIT |
| Input voltage (V_{IN}) | 4.5 | - | 60 | V |
| Control input voltage (V_{CIN}) ⁽¹⁾ | 4.5 | - | 60 | |
| Enable (EN) | 0 | - | 60 | |
| Bias supply (V_{DD}) | 4.75 | 5 | 5.25 | |
| Drive supply voltage (V_{DRV}) | 4.75 | 5.3 | 5.55 | |
| Output voltage (V_{OUT}) | 0.8 | - | $0.92 \times V_{IN}$ | |
| Temperature | | | | |
| Recommended ambient temperature | -40 to +105 | | | °C |
| Operating junction temperature | -40 to +125 | | | |

Note

⁽¹⁾ For input voltages below 5 V, provide a separate supply to V_{CIN} of at least 5 V to prevent the internal V_{DD} rail UVLO from triggering

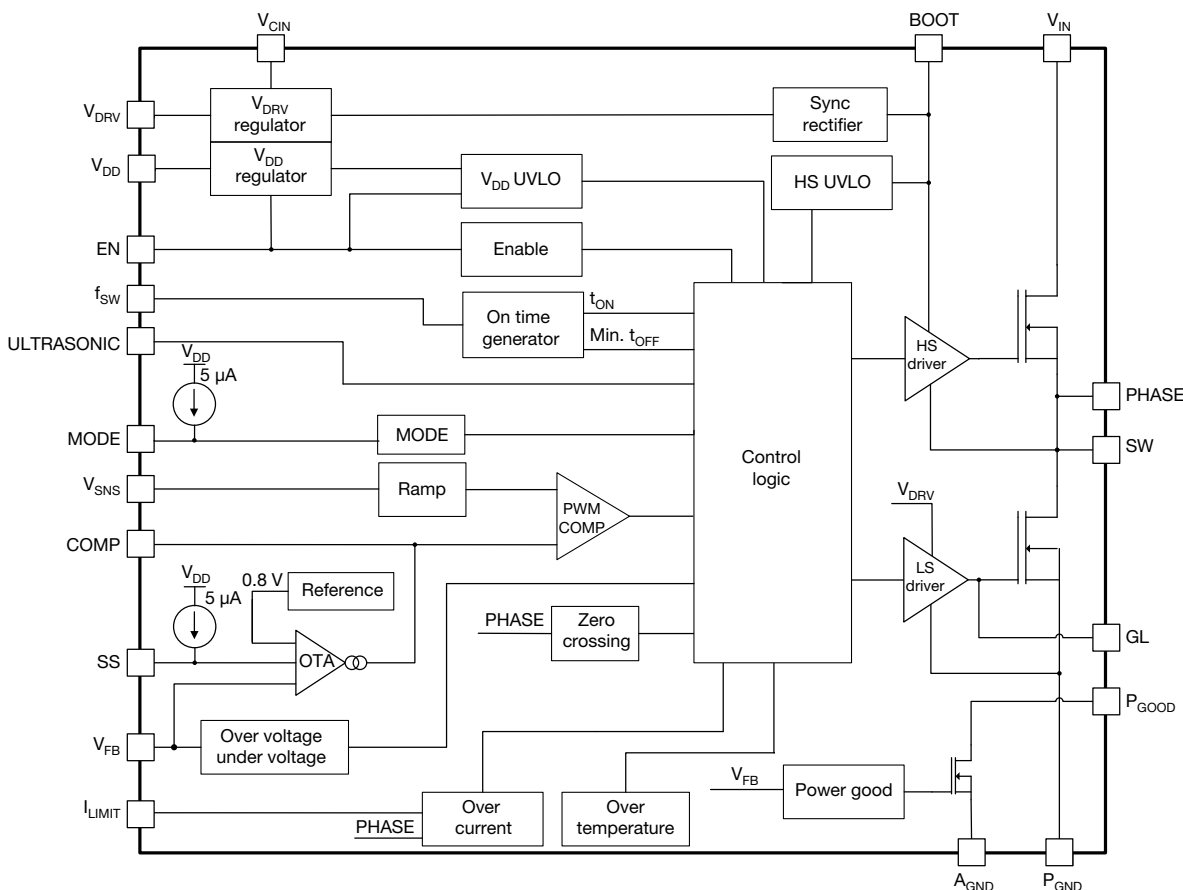
| ELECTRICAL SPECIFICATIONS ($V_{IN} = V_{CIN} = 48 V$, $V_{EN} = 5 V$, $T_J = -40\text{ }^\circ\text{C}$ to $+125\text{ }^\circ\text{C}$, unless otherwise stated) | | | | | | |
|--|-----------------------|--|------|------|------|---------------|
| PARAMETER | SYMBOL | TEST CONDITIONS | MIN. | TYP. | MAX. | UNIT |
| Power Supplies | | | | | | |
| V_{DD} supply | V_{DD} | $V_{IN} = V_{CIN} = 6 V$ to $60 V$ | 4.75 | 5 | 5.25 | V |
| | | $V_{IN} = V_{CIN} = 5 V$ | 4.7 | 5 | - | |
| V_{DD} dropout | $V_{DD_DROPOUT}$ | $V_{IN} = V_{CIN} = 5 V$, $I_{VDD} = 1\text{ mA}$ | - | 70 | - | mV |
| V_{DD} UVLO threshold, rising | V_{DD_UVLO} | | 4 | 4.25 | 4.5 | V |
| V_{DD} UVLO hysteresis | $V_{DD_UVLO_HYST}$ | | - | 225 | - | mV |
| Maximum V_{DD} current | I_{DD} | $V_{IN} = V_{CIN} = 6 V$ to $60 V$ | 3 | - | - | mA |
| V_{DRV} supply | V_{DRV} | $V_{IN} = V_{CIN} = 6 V$ to $60 V$ | 5.1 | 5.3 | 5.55 | V |
| | | $V_{IN} = V_{CIN} = 5 V$ | 4.8 | 5 | 5.2 | |
| V_{DRV} dropout | $V_{DRV_DROPOUT}$ | $V_{IN} = V_{CIN} = 5 V$, $I_{VDD} = 10\text{ mA}$ | - | 160 | - | mV |
| Maximum V_{DRV} current | V_{DRV} | $V_{IN} = V_{CIN} = 6 V$ to $60 V$ | 50 | - | - | mA |
| V_{DRV} UVLO threshold, rising | V_{DRV_UVLO} | | 4 | 4.25 | 4.5 | V |
| V_{DRV} UVLO hysteresis | $V_{DRV_UVLO_HYST}$ | | - | 295 | - | mV |
| Input current | I_{VCIN} | Non-switching, $V_{FB} > 0.8 V$ | - | 235 | 325 | μA |
| Shutdown current | I_{VCIN_SHDN} | $V_{EN} = 0 V$ | - | 4 | 8 | |
| Controller and Timing | | | | | | |
| Feedback voltage | V_{FB} | $T_J = 25\text{ }^\circ\text{C}$ | 796 | 800 | 804 | mV |
| | | $T_J = -40\text{ }^\circ\text{C}$ to $+125\text{ }^\circ\text{C}$ ⁽¹⁾ | 792 | 800 | 808 | |
| V_{FB} input bias current | I_{FB} | | - | 2 | - | nA |
| Transconductance | g_m | | - | 0.3 | - | mS |
| COMP source current | I_{COMP_SOURCE} | | 15 | 20 | - | μA |
| COMP sink current | I_{COMP_SINK} | | 15 | 20 | - | |
| Minimum on-time | $t_{ON_MIN.}$ | | - | 90 | 110 | ns |
| t_{ON} accuracy | $t_{ON_ACCURACY}$ | | -10 | - | 10 | % |
| On-time range | t_{ON_RANGE} | | 110 | - | 8000 | ns |
| Frequency range | f_{sw} | Ultrasonic mode enabled | 20 | - | 2000 | kHz |
| | | Ultrasonic mode disabled | 0 | - | 2000 | |
| Minimum off-time | $t_{OFF_MIN.}$ | | 190 | 250 | 310 | ns |
| Soft start current | I_{SS} | | 3 | 5 | 7 | μA |
| Soft start voltage | V_{SS} | When V_{OUT} reaches regulation | - | 1.5 | - | V |



| ELECTRICAL SPECIFICATIONS ($V_{IN} = V_{CIN} = 48\text{ V}$, $V_{EN} = 5\text{ V}$, $T_J = -40\text{ }^\circ\text{C}$ to $+125\text{ }^\circ\text{C}$, unless otherwise stated) | | | | | | |
|--|----------------------------|---|------|------|------|------------------|
| PARAMETER | SYMBOL | TEST CONDITIONS | MIN. | TYP. | MAX. | UNIT |
| Fault Protections | | | | | | |
| Valley current limit | I_{OCP} | SiC461 (10 A), $R_{ILIM} = 60\text{ k}\Omega$, $T_J = -10\text{ }^\circ\text{C}$ to $+125\text{ }^\circ\text{C}$ | 10.4 | 13 | 15.6 | A |
| | | SiC462 (6 A), $R_{ILIM} = 60\text{ k}\Omega$, $T_J = -10\text{ }^\circ\text{C}$ to $+125\text{ }^\circ\text{C}$ | 6.4 | 8 | 9.6 | |
| | | SiC463 (4 A), $R_{ILIM} = 40\text{ k}\Omega$, $T_J = -10\text{ }^\circ\text{C}$ to $+125\text{ }^\circ\text{C}$ (2) | 4.8 | 6 | 7.2 | |
| | | SiC464 (2 A), $R_{ILIM} = 60\text{ k}\Omega$, $T_J = -10\text{ }^\circ\text{C}$ to $+125\text{ }^\circ\text{C}$ | 3.2 | 4 | 4.8 | |
| Output OVP threshold | V_{OVP} | V_{FB} with respect to 0.8 V reference | - | 20 | - | % |
| Output UVP threshold | V_{UVP} | | - | -80 | - | |
| Over temperature protection | T_{OTP_RISING} | Rising temperature | - | 150 | - | $^\circ\text{C}$ |
| | T_{OTP_HYST} | Hysteresis | - | 35 | - | |
| Power Good | | | | | | |
| Power good output threshold | $V_{FB_RISING_VTH_OV}$ | V_{FB} rising above 0.8 V reference | - | 20 | - | % |
| | $V_{FB_FALLING_VTH_UV}$ | V_{FB} falling below 0.8 V reference | - | -10 | - | |
| Power good hysteresis | V_{FB_HYST} | | - | 50 | - | mV |
| Power good on resistance | R_{ON_PGOOD} | | - | 7.5 | 15 | Ω |
| Power good delay time | t_{DLY_PGOOD} | | 15 | 25 | 35 | μs |
| EN / MODE / Ultrasonic Threshold | | | | | | |
| EN logic high level | V_{EN_H} | | - | 1.35 | - | V |
| EN logic low level | V_{EN_L} | | - | 1.2 | - | |
| EN hysteresis | V_{HYST} | | - | 0.15 | - | |
| EN pull down resistance | R_{EN} | | - | 5 | - | $M\Omega$ |
| Ultrasonic mode high Level | $V_{ULTRASONIC_H}$ | | 2 | - | - | V |
| Ultrasonic mode low level | $V_{ULTRASONIC_L}$ | | - | - | 0.8 | |
| Mode pull up current | I_{MODE} | | 3.75 | 5 | 6.25 | μA |
| Mode 1 | R_{MODE} | Power save mode enabled, V_{DD} , V_{DRV} Pre-reg on | 0 | 2 | 100 | $k\Omega$ |
| Mode 2 | | Power save mode disabled, V_{DD} , V_{DRV} Pre-reg on | 298 | 301 | 304 | |
| Mode 3 | | Power save mode disabled, V_{DRV} Pre-reg off, V_{DD} Pre-reg on, provide external V_{DRV} | 494 | 499 | 504 | |
| Mode 4 | | Power save mode enabled, V_{DRV} Pre-reg off, V_{DD} Pre-reg on, provide external V_{DRV} | 900 | 1000 | 1100 | |

Notes

- (1) Guaranteed by design
- (2) Guaranteed by design for SiC463 OCP measurements

FUNCTIONAL BLOCK DIAGRAM

Fig. 4 - SiC46x Functional Block Diagram
OPERATIONAL DESCRIPTION
Device Overview

SiC46x is a high efficiency synchronous buck regulator family capable of delivering up to 10 A continuous current. The device has programmable switching frequency of 100 kHz to 2 MHz. The voltage mode, constant on time control scheme delivers fast transient response, minimizes the number of external components and enables loop stability regardless of the type of output capacitor used, including low ESR ceramic capacitors. The device also incorporates a power saving feature that enables diode emulation mode and frequency fold back as the load decreases.

SiC46x has a full set of protection and monitoring features:

- Over current protection in pulse-by-pulse mode
- Output overvoltage protection
- Output undervoltage protection with auto retry
- Over temperature protection with hysteresis
- Dedicated enable pin for easy power sequencing
- Power good open drain output
- This device is available in MLP55-27L package to deliver high power density and minimize PCB area

Power Stage

SiC46x integrates a high performance power stage with a n-channel high side MOSFET and a n-channel low side MOSFET optimized to achieve up to 98 % efficiency.

The power input voltage (V_{IN}) can go up to 60 V and down as low as 4.5 V for power conversion.

Control Scheme

SiC46x employs a voltage mode COT control mechanism in conjunction with adaptive zero current detection which allows for power saving in discontinuous conduction mode (DCM). The switching frequency, f_{SW} , is set by an external resistor to A_{GND} , R_{fsw} . The SiC46x operates between 100 kHz to 2 MHz depending on V_{IN} and V_{OUT} conditions.

$$R_{fsw} = \frac{V_{OUT}}{f_{SW} \times 190 \times 10^{-12}}$$

Note, as long as V_{IN} and V_{CIN} are connected together, f_{SW} has no dependency on V_{IN} as the on time is adjusted as V_{IN} varies. During steady-state operation, feedback voltage (V_{FB}) is compared with internal reference (0.8 V typ.) and the amplified error signal (V_{COMP}) is generated at the comp node by the external compensation components, R_{COMP} and C_{COMP} . An externally generated ramp signal and V_{COMP} feed into a comparator. Once V_{RAMP} crosses V_{COMP} , an on-time

pulse is generated for a fixed time. During the on-time pulse, the high side MOSFET will be turned on. Once the on-time pulse expires, the low side MOSFET will be turned on after a dead time period. The low side MOSFET will stay on for a minimum duration equal to the minimum off-time (t_{OFF_MIN}) and remains on until V_{RAMP} crosses V_{COMP} . The cycle is then repeated.

Fig. 6 illustrates the basic block diagram for voltage mode, constant on time architecture with external ripple injection, V_{RAMP} , while Fig. 5 illustrates the basic operational principle.

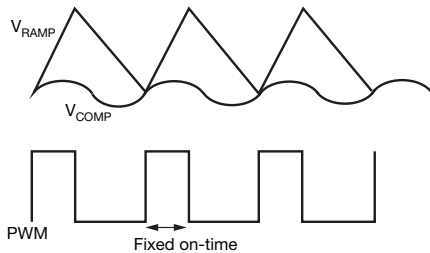


Fig. 5 - SiC46x Operational Principle

The need for ripple injection in this architecture is explained below. First, let us understand the basic principles of this control architecture:

- The reference of a basic voltage mode COT regulator is replaced with a high gain error amplifier loop. The loop ensures the DC component of the output voltage follows the internal accurate reference voltage, providing excellent regulation
- A second voltage feedback path via V_{SNS} with a V_{RAMP} scheme ensures rapid correction of the transient perturbation
- This establishes two voltage loops, one is the steady state voltage feedback path (via the FB pin) and the other is the feed forward path (via the V_{SNS} pin). The scheme gives the user the fast transient response of a COT regulator and the stable, jitter free, line and load regulation performance of a PWM controller

Choosing the Ripple Injection Component Values

For stability purposes the SiC46x requires adequate ripple injection amplitude. Adequate ripple amplitude is required for two main reasons:

1. To reduce jitter due to noise coupled into the system
2. To provide stable operation. Sub harmonic oscillation can occur with constant on time ripple control if below condition is not met

$$ESR \times C_{OUT} > \frac{t_{ON}}{2}$$

Therefore, when the converter design uses an all ceramic output capacitor or other low ESR output capacitors, instability can occur. In order to avoid this, a V_{RAMP} network is used to increase the equivalent R_{ESR} in order to satisfy the above condition. The V_{RAMP} amplitude must be large enough to avoid instability or noise sensitivity but not too large that it degrades transient performance. To ensure stable operation under CCM, DCM and ultrasonic mode, minimum V_{RAMP} amplitude of 100 mV is recommended for the SiC46x family of regulators. A maximum V_{RAMP} of 900 mV is recommended so as not to degrade transient response.

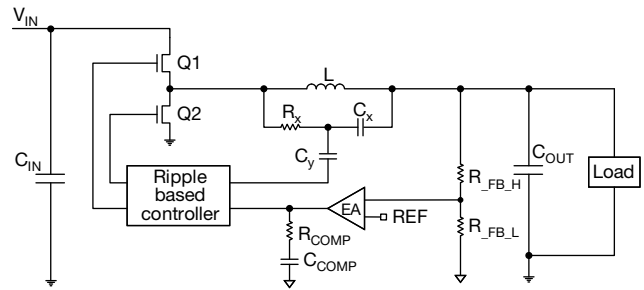


Fig. 6 - SiC46x Control Block Diagram

Below is the equation for calculating the V_{RAMP} amplitude.

$$V_{RAMP} = \frac{(V_{IN} - V_{OUT}) \times V_{OUT}}{(V_{IN} \times f_{sw} \times C_X \times R_X)}$$

V_{RAMP} amplitude is a function of V_{IN} , V_{OUT} , and switching frequency and should be adjusted whenever V_{IN} , V_{OUT} , or switching frequency is changed.

For a given buck regulator design, V_{OUT} and switching frequency is typically fixed, while the converter may be expected to work for a wide V_{IN} range. The V_{RAMP} amplitude will increase as V_{IN} is increased and increase the power dissipated by R_X . A proper selection of R_X , package size and value, should take into account the maximum power dissipation at the expected operating conditions.

In order to optimize the V_{RAMP} amplitude over a desired V_{IN} range use the following procedure to calculate R_X , C_X , and C_Y .

1. The equation below calculates R_X as a function of V_{IN} , V_{OUT} , and maximum allowable power dissipated by R_X .

$$R_X = \frac{V_{IN_MAX} \times V_{OUT} \times (1 - D)}{P_{RX_MAX}}$$

where P_{RX_MAX} is the maximum allowed power dissipation in R_X . Note, the maximum power dissipation of a 0603 sized resistor is typically 25 mW. Power dissipation derating must be taken into account for high ambient temperatures

2. The equation below calculates C_{X_MIN} as a function of V_{IN} and maximum allowed V_{RAMP} amplitude.

$$C_{X_MIN} = \frac{P_{RX_MAX}}{V_{IN_MAX} \times f_{sw} \times V_{RAMP_MAX}}$$

where $V_{RAMP_MAX} = 900$ mV

3. Using V_{RAMP} equation, calculate V_{RAMP_MIN} at minimum V_{IN} based on the R_X and the minimum C_X value calculated above
4. If V_{RAMP_MIN} is > 200 mV, set C_X to C_{X_MIN} , otherwise set C_X to $(C_{X_MIN} \times V_{RAMP_MIN} / 200 \text{ mV})$. If V_{RIPPLE_MIN} is < 100 mV, increase P_{RX_MAX} and recalculate R_X and C_X
5. C_Y should be large enough not to distort the V_{RAMP} and small enough not to load excessively the V_{RAMP} network (R_X and C_X). Please use the follow formula: $C_Y = 1 / (0.82 \times f_{sw})$

This procedure allows for a maximum range of operation. In order to simplify the procedure for calculating V_{RAMP} and compensation components, a calculator is provided (visit www.vishay.com/doc?65124).



Error Amplifier Compensation Value Selection (for reference only)

R_{COMP} and C_{COMP} in the Fig. 6 are the components used to compensate the control loop.

For optimal transient response, the crossover frequency should be:

- Set typically at 1/10th to 1/5th of the converter switching frequency (Vishay’s component calculator tool uses 1/10th the converter switching frequency)
- Be above the LC filter resonance frequency which is $1/2 \pi \sqrt{LC}$

The procedure to select the R_{COMP} and C_{COMP} such that the above conditions are met is as follows:

1. Plot the magnitude and phase of the control to output transfer function using the equation below.
Control to output transfer function.

$$H(s) = A \times \frac{1 + sR_C C_o \times (1 + sR_x C_x) \times (1 + sR_y C_y)}{\left(1 + \frac{sL}{R_o} + s^2 LC_o\right) \times (1 + sR_x C_x) \times (1 + sR_y C_y) + AR_y C_y s \times \left[1 + s \times \left(R_x C_x + \frac{L}{R_o}\right) + s^2 \times (R_x R_c C_x C_o + LC_o)\right]}$$

Where A = (2V_{IN} × R_x × C_x × f)/V_{OUT}, R_x, C_x, C_y are components for ripple injection as shown in Fig. 6 and R_y is the internal impedance of the V_{SNS} pin and is = 65 kΩ.

C_o - output capacitance
R_c - output capacitor ESR

2. From the plot of the control to output transfer function, determine the gain and phase at the crossover frequency
3. Calculate the R_{COMP} using the equation

$$R_{COMP} = \frac{1}{G_H \times g_m \times r_{FB}}$$

where G_H is the gain of the transfer function at cross over frequency, “g_m” is the transconductance of the error amplifier (300 μS) and r_{FB} is the ratio of the feedback divider, r_{FB} = R_{FB_L}/(R_{FB_L} + R_{FB_H})

4. Select C_{COMP} based on the placement of the zero such that phase margin is sufficient at the cross over frequency. A phase margin of over 60° is sufficient for converter stability. A good starting point is to place the compensation zero at 1/5th of the LC pole

$$C_{COMP} = \frac{5 \sqrt{LC}}{R_{COMP}}$$

Once the component values are calculated, it is now possible to calculate the total loop gain. The total loop gain is the product of the control to output transfer function and the error amplifier transfer function.

The transfer function of the error amplifier is given by the equation below.

$$G(s) = g_m R_o \times \frac{(1 + sR_{COMP} C_{COMP}) \times r_{FB}}{(1 + s \times (R_{COMP} C_{COMP} + R_o C_{COMP}))}$$

Where R_o = 40 MΩ is the output resistance of the transconductance amplifier.

Total loop transfer function = H(s)G(s)

An automated calculator (visit www.vishay.com/doc?75760) is provided to assist the user to determine V_{RAMP} components as well as error amplifier compensation components using user selected operating conditions.

Power-Save Mode, Mode Pin, and Ultrasonic Pin Operation

To improve efficiency at light-loads, SiC46x provides a set of innovative implementations to reduce low side re-circulating current and switching losses. The internal zero crossing detector monitors SW node voltage to determine when inductor current starts to flow negatively. In power saving mode, as soon as inductor current crosses zero, the device first deploys diode mode by turning off the low side MOSFET. If load further decreases, switching frequency is reduced proportional to the load condition to save switching losses while keeping output ripple within tolerance. If the ultrasonic pin is tied to V_{DD} , the minimum switching frequency in discontinuous mode is > 20 kHz to avoid switching frequencies in the audible range. If this feature is not required ultrasonic mode can be disabled by floating the ULTRASONIC pin. When ultrasonic mode is disabled, the regulator will operate in forced continuous mode or power save mode where there is no limit to the lower frequency limit. In this state, at zero load, switching frequency can go as low as hundreds of hertz.

OUTPUT MONITORING AND PROTECTION FEATURES

Output Over-Current Protection (OCP)

SiC46x has pulse-by-pulse over current limit control. The inductor current is monitored during low side MOSFET conduction time through $R_{DS(on)}$ sensing. After a pre-defined blanking time, the inductor current is compared with an internal OCP threshold. If inductor current is higher than OCP threshold, high side MOSFET is kept off until the inductor current falls below OCP threshold.

OCP is enabled immediately after V_{DD} passes UVLO level. OCP is set by an external resistor, R_{LIM} to A_{GND} . (See table 2)

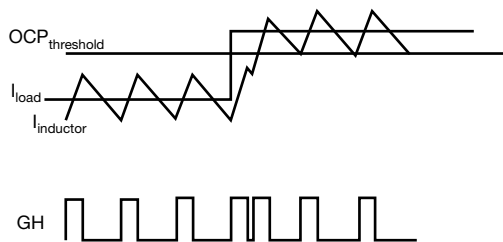


Fig. 7 - Over-Current Protection Illustration

Output Undervoltage Protection (UVP)

UVP is implemented by monitoring the FB pin. If the voltage level at FB drops below 0.16 V for more than 25 μ s, a UVP event is recognized and both high side and low side MOSFETs are turned off. After a duration equivalent to 20 soft start periods, the IC attempts to re-start. If the fault condition still exists, the above cycle will be repeated.

UVP is only active after the completion of soft-start sequence.

Output Over Voltage Protection (OVP)

OVP is implemented by monitoring the FB pin. If the voltage level at FB rising above 0.96 V, a OVP event is recognized and both high side and low side MOSFETs are turned off. Normal operation is resumed once FB voltage drop below 0.91 V.

To improve the converter efficiency, the user can choose to disable the internal V_{DRV} regulator by picking either mode 3 or mode 4 and connecting a 5 V supply to the V_{DRV} pin. This reduces power dissipation in the SiC46x by eliminating the V_{DRV} linear regulator losses.

The mode pin supports several modes of operation as shown in table 1. An internal current source is used to set the voltage on this pin using an external resistor:

TABLE 1 - OPERATION MODES

| MODE | RANGE (k Ω) | POWER SAVE MODE | INTERNAL V_{DRV} REGULATOR |
|------|---------------------|-----------------|------------------------------|
| 1 | 0 to 100 | Enabled | ON |
| 2 | 298 to 304 | Disabled | ON |
| 3 | 494 to 504 | Disabled | OFF ⁽¹⁾ |
| 4 | 900 to 1100 | Enabled | OFF ⁽¹⁾ |

Note

⁽¹⁾ Connect a 5 V (± 5 %) supply to the V_{DRV} pin

The mode pin is not latched to any state and can be changed on the fly.

Over Temperature Protection (OTP)

OTP is implemented by monitoring the junction temperature. If the junction temperature rises above 150 $^{\circ}$ C, a OTP event is recognized and both high side and low MOSFETs are turned off. After the junction temperature falls below 115 $^{\circ}$ C (35 $^{\circ}$ C hysteresis), the device restarts by initiating a soft start sequence.

Sequencing of Input / Output Supplies

SiC46x has no sequencing requirements on its supplies or enables (V_{IN} , V_{CIN} , V_{DD} , V_{DRV} , EN).

Enable

The SiC46x has an enable pin to turn the part on and off. Driving this pin above 1.35 V enables the device, while driving the pin below 1.2 V disables the device.

The EN pin is internally pulled to A_{GND} by a 5 M Ω resistor to prevent unwanted turn on due to a floating GPIO.

Soft-Start

During soft start time period, inrush current is limited and the output voltage is ramped gradually. The following control scheme is implemented:

Once the V_{DD} voltage reaches the UVLO trip point, an internal "Soft start Reference" (SR) begins to ramp up. The SR ramp rate is determined by the external soft start capacitor and an internal 5 μ A current source tied to the soft start pin.

The internal SR signal is used as a reference voltage to the error amplifier (see functional block diagram). The control scheme guarantees that the output voltage during the soft start interval will ramp up coincidentally with the SR voltage. The soft-start time, t_{SS} , is adjustable by calculating a capacitor value from the following equation.

$$t_{SS} = \frac{C_{SS} \times 0.8 \text{ V}}{5 \mu\text{A}}$$

During soft-start period, OCP is activated. Short circuit protection is not active until soft-start is complete.

Pre-Bias Start-Up

In case of pre-bias startup, output is monitored through FB pin. If the sensed voltage on FB is higher than the internal reference ramp value, control logic prevents high side and low side MOSFETs from switching to avoid negative output voltage spike and excessive current sinking through low side MOSFET.

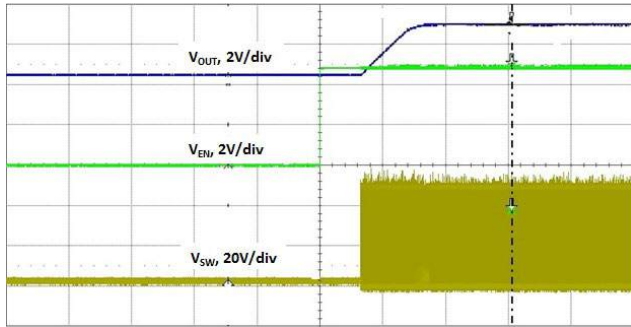


Fig. 8 - Pre-Bias Start-Up

Power Good

SiC46x's power good is an open-drain output. Pull P_{GOOD} pin high through a > 10K resistor to use this signal. Power good window is shown in Fig. 9. If voltage on FB pin is out of this window, P_{GOOD} signal is de-asserted by pulling down to A_{GND}. To prevent false triggering during transient events, P_{GOOD} has a 25 μs blanking time.

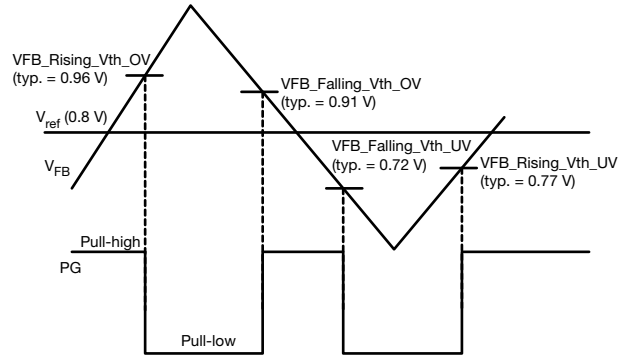


Fig. 9 - P_{GOOD} Window

EXAMPLE SCHEMATIC OF SiC462

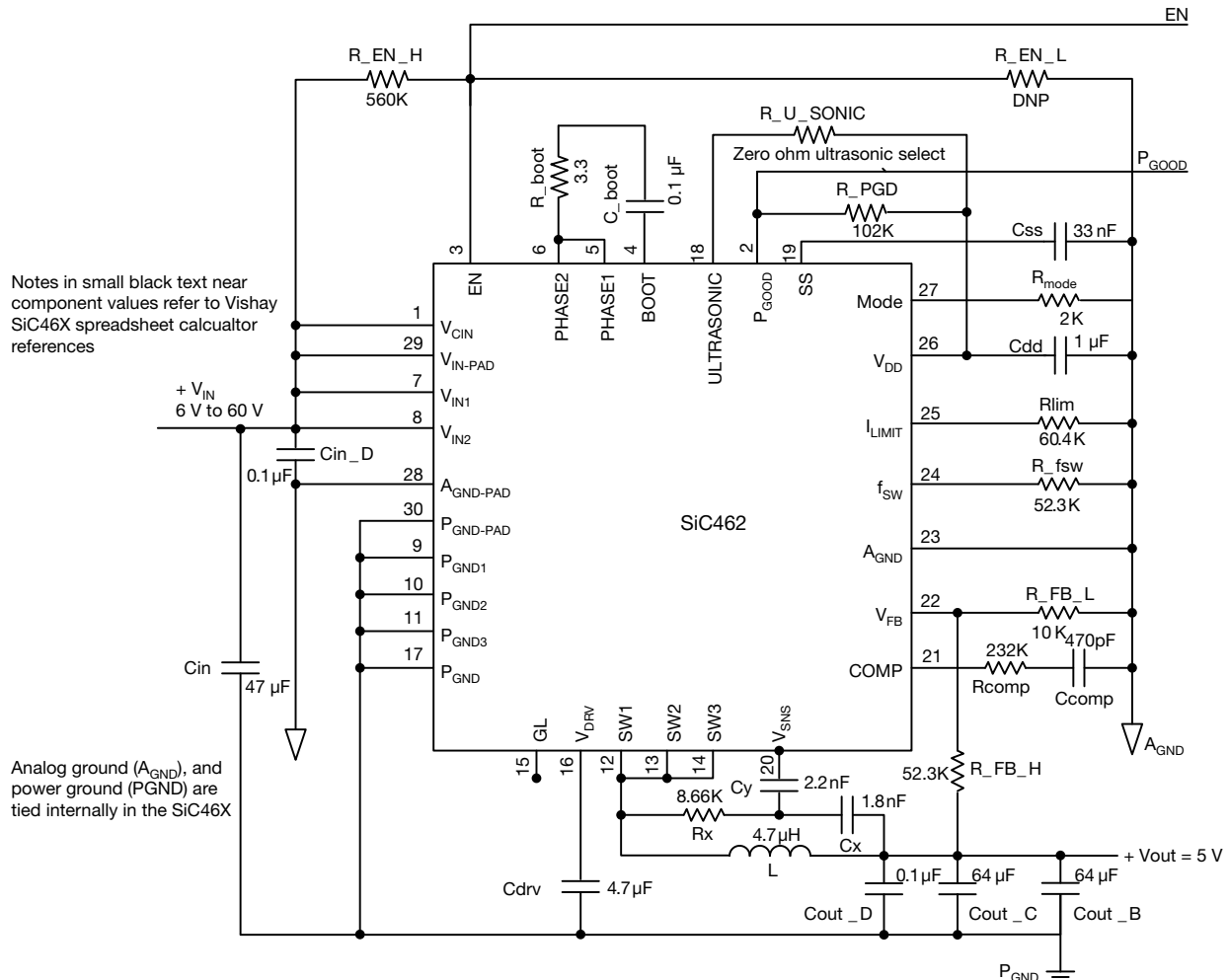


Fig. 10 - SiC462 Configured for 6 V to 60 V Input, 5 V Output at 6 A, 500 kHz Operation with Ultrasonic Power Save Mode Enabled



all Ceramic Output Capacitance Design

EXTERNAL COMPONENT SELECTION FOR THE SiC46x

This section explains external component selection for the SiC46x family of regulators. Component reference designators in any equation refer to the schematic shown in Fig. 10.

An excel based calculator is available on the website to make external component calculation simple. The user simply needs to enter required operating conditions.

Output Voltage Adjustment

If a different output voltage is needed, simply change the value of V_{OUT} and solve for R_{FB_H} based on the following formula:

$$R_{FB_H} = \frac{R_{FB_L}(V_{OUT} - V_{FB})}{V_{FB}}$$

where V_{FB} is 0.8 V. R_{FB_L} should be a maximum of 10 k Ω to prevent V_{OUT} from drifting at no load.

Switching Frequency Selection

The following equation illustrates the relationship between frequency, V_{IN} , V_{OUT} , and R_{fsw} value:

$$R_{fsw} = \frac{V_{OUT}}{f_{sw} \times (190 \times 10^{-12})}$$

Inductor Selection

In order to determine the inductance, the ripple current must first be defined. Low inductor values allow for the use of smaller package sizes but create higher ripple current which can reduce efficiency. Higher inductor values will reduce the ripple current and, for a given DC resistance, are more efficient. However, larger inductance translates directly into larger packages and higher cost. Cost, size, output ripple, and efficiency are all used in the selection process.

The ripple current will also set the boundary for power save operation. The SiC46x will typically enter power save mode when the load current decreases to 1/2 of the ripple current. For example, if ripple current is 1.8 A, power save operation will be active for loads less than 0.9 A. If ripple current is set at 30 % of maximum load current, power save will typically start at a load which is 15 % of maximum current.

The inductor value is typically selected to provide ripple current of 25 % to 50 % of the maximum load current. This provides an optimal trade-off between cost, efficiency, and transient performance. During the on-time, voltage across the inductor is $(V_{IN} - V_{OUT})$. The equations for determining inductance are shown below.

$$t_{ON} = \frac{V_{OUT}}{V_{IN} \times f_{sw}}$$

and

$$L = \frac{(V_{IN} - V_{OUT}) \times t_{ON}}{I_{OUT_MAX} \times K}$$

where, K is the maximum percentage of ripple current. The designer can quickly make a choice of inductor if the ripple

percentage is decided, usually no more than 30 % however higher or lower percentages of I_{OUT} can be acceptable depending on application. This device allows choices larger than 30 %.

Other than the inductance the DCR and saturation current parameters are key values. The DCR causes an I^2R loss which will decrease the system efficiency and generate heat. The saturation current has to be higher than the maximum output current plus 1/2 of the ripple current. In an over current condition the inductor current may be very high. All this needs to be considered when selecting the inductor.

Output Capacitor Selection

The SiC46x is stable with any type of output capacitors by choosing the appropriate V_{RAMP} components. This allows the user to choose the output capacitance based on the best trade off of board space, cost and application requirements.

The output capacitors are chosen based upon required ESR and capacitance. The maximum ESR requirement is controlled by the output ripple voltage requirement and the DC tolerance. The output voltage has a DC value that is equal to the valley of the output ripple plus half of the peak-to-peak ripple. A change in the output ripple voltage will lead to a change in DC voltage at the output. The relationship between output voltage ripple, output capacitance and ESR of the output capacitor is shown by the following equation:

$$V_{RIPPLE} = I_{RIPPLE(MAX.)} \times \left(\frac{1}{8 \times C_o \times f_{sw}} + ESR \right) \quad (1)$$

Where V_{RIPPLE} is the maximum allowed output ripple voltage; $I_{RIPPLE(MAX.)}$ is the maximum inductor ripple current; f_{sw} is the switching frequency of the converter; C_o is the total output capacitance; ESR is the equivalent series resistance of the total output capacitors.

In addition to the output ripple voltage requirement, the output capacitors need to meet transient requirements. A worst case load release condition (from maximum load to no load at the exact moment when inductor current is at the peak) determines the required capacitance. If the load release is instantaneous (load changes from maximum to zero within 1 μ s), the output capacitor must absorb all the energy stored in the inductor. The peak voltage on the capacitor, V_{PK} , under this worst case condition can be calculated by following equation:

$$C_{OUT_MIN.} = \frac{L \times \left(I_{OUT} + \frac{1}{2} \times I_{RIPPLE(MAX.)} \right)^2}{(V_{PK})^2 - (V_{OUT})^2} \quad (2)$$

During the load release time, the voltage across the inductor is approximately $-V_{OUT}$. This causes a down-slope or falling di/dt in the inductor. If the load di/dt is not much faster than the di/dt of the inductor, then the inductor current will tend to track the falling load current. This will reduce the excess inductive energy that must be absorbed by the output



capacitor; therefore a smaller capacitance can be used. The following can be used to calculate the required capacitance for a given di_{LOAD}/dt .

Peak inductor current, I_{LPK} , is shown by the next equation:

$$I_{LPK} = I_{MAX.} + \frac{1}{2} \times I_{RIPPLE(MAX.)}$$

The slew rate of load current = $\frac{di_{LOAD}}{dt}$

$$C_{OUT_MIN.} = I_{LPK} \times \frac{L \times \frac{I_{LPK}}{V_{OUT}} - \frac{I_{MAX.}}{di_{LOAD}} \times dt}{2(V_{PK} - V_{OUT})} \quad (3)$$

Based on application requirement, either equation (2) or equation (3) can be used to calculate the ideal output capacitance to meet transition requirement. Compare this calculated capacitance with the result from equation (1) and choose the larger value to meet both ripple and transition requirement.

Enable Pin Voltage

The EN pin has an internal 5 MΩ pull down resistor connected to A_{GND} . In order to enable the device, an external signal greater than 1.4 V is required. The enable can also be used to set the minimum V_{CIN} , V_{IN} startup voltage by connecting a voltage divider between V_{IN} , EN, and P_{GND} . An automated calculator is available to assist in component selection.

Current Limit Resistor

The current limit is set by placing a resistor between I_{LIM} and A_{GND} . The values can be found using the following equation:

$$R_{LIM} (k\Omega) = \frac{K_{LIM}}{I_{OUT_MAX.} - \frac{(V_{IN} - V_{OUT}) \times V_{OUT}}{2 \times f_{sw} \times V_{IN} \times L}}$$

Where

- $I_{OUT_MAX.}$ is desired DC current limit level
- K_{LIM} is determined by Table 2

| TABLE 2 - K_{LIM} VALUE | |
|---------------------------|-----------|
| PART NUMBER | K_{LIM} |
| SiC461 | 780K |
| SiC462 | 480K |
| SiC463 | 240K |
| SiC464 | 240K |

Note

- It is suggested that the current limit setting not be higher than 2 times the rated current of the part. Be sure max. current limit is within the saturation current of the inductor

Input Capacitance

In order to determine the minimum capacitance the input voltage ripple needs to be specified; $V_{IN_PK-PK} \leq 500$ mV is a

suitable starting point. This magnitude is determined by the final application specification. The input current needs to be determined for the lowest operating input voltage,

$$I_{VCIN(RMS)} = I_O \times \sqrt{D \times (1 - D) + \frac{1}{12} \times \left(\frac{V_{OUT}}{L \times f_{sw} \times I_{OUT}} \right)^2 \times (1 - D)^2 \times D}$$

The minimum input capacitance can then be found,

$$C_{VIN_MIN.} = I_{OUT} \times \frac{D \times (1 - D)}{V_{IN_PK-PK} \times f_{sw}}$$

If high ESR capacitors are used, it is good practice to also add low ESR ceramic capacitance. A 4.7 μF ceramic input capacitance is a suitable starting point.

Note, account for voltage derating of capacitance when using all ceramic input capacitors.

Efficiency Measurement

Fig. 11 to 39 in the following pages are the efficiency data for the SiC461, SiC462, SiC463, and SiC464.

The measurements are taken based on the Vishay 6 layers, 2 ounce copper evaluation board.

The inductors used in the measurement are tabulated below.

| TABLE 3 - INDUCTOR VALUES | | | |
|---------------------------|-----------------|----------------------|----------|
| DEVICE PART | INDUCTANCE (μH) | INDUCTOR PART NUMBER | DCR (mΩ) |
| SiC461 | 3.3 | IHLP6767GZER3R3M11 | 2.79 |
| | 4.7 | IHLP6767GZER4R7M11 | 3.98 |
| | 6.8 | IHLP6767GZER6R8M11 | 5.86 |
| | 8.2 | IHLP6767GZER8R2M11 | 7.71 |
| | 10 | IHLP6767GZER100M11 | 8.89 |
| SiC462 | 5.6 | IHLP5050FDER5R6M51 | 8.51 |
| | 6.8 | IHLP5050FDER6R8M51 | 11.30 |
| | 8.2 | IHLP5050FDER8R2M51 | 13.20 |
| | 10 | IHLP5050FDER100M51 | 16.60 |
| | 15 | IHLP5050FDER150M51 | 24.00 |
| SiC463 | 10 | IHLP5050FDER100M51 | 16.60 |
| | 15 | IHLP5050FDER150M51 | 24.00 |
| | 22 | IHLP5050FDER220M51 | 31.30 |
| SiC464 | 10 | IHLP5050FDER100M51 | 16.60 |
| | 15 | IHLP5050FDER150M51 | 24.00 |
| | 22 | IHLP5050FDER220M51 | 31.30 |



ELECTRICAL CHARACTERISTICS (VIN = 48 V, VOUT = 5 V, fsw = 300 kHz, SiC461 (10 A), unless otherwise noted)

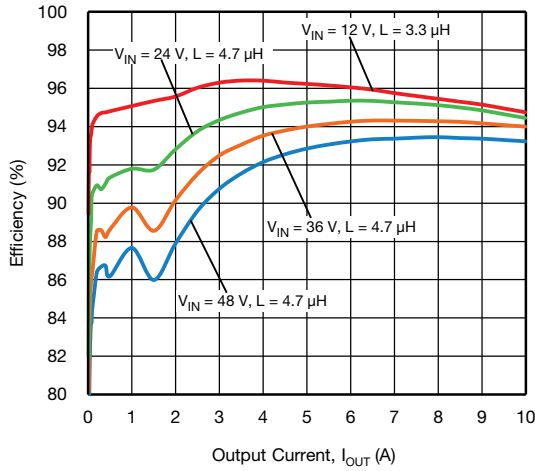


Fig. 11 - SiC461 Efficiency vs. Output Current, VOUT = 5 V

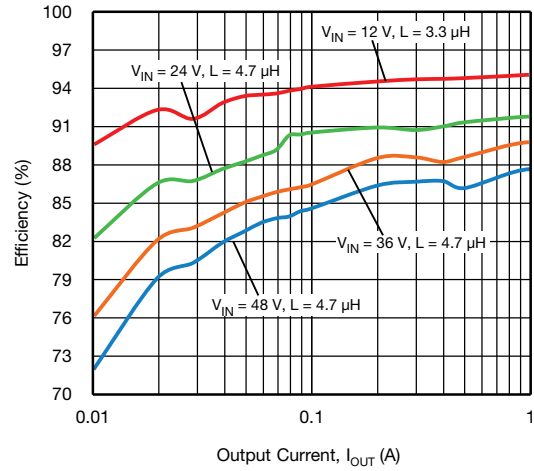


Fig. 14 - SiC461 Efficiency vs. Output Current - Light Load, VOUT = 5 V

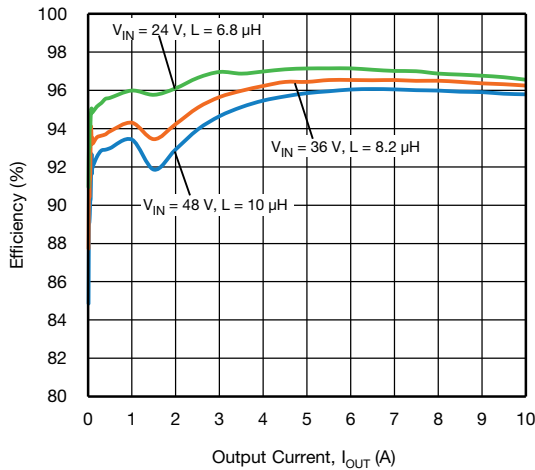


Fig. 12 - SiC461 Efficiency vs. Output Current, VOUT = 12 V

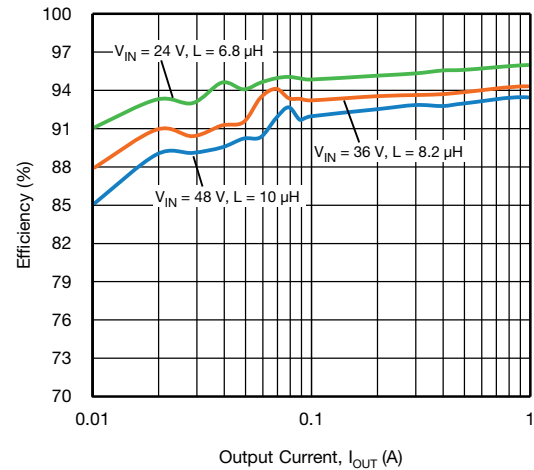


Fig. 15 - SiC461 Efficiency vs. Output Current - Light Load, VOUT = 12 V

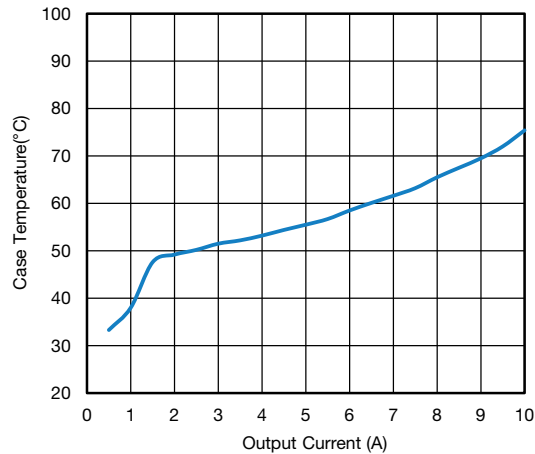


Fig. 13 - SiC461 Load Current vs. Case Temperature, VIN = 48 V, VOUT = 5 V

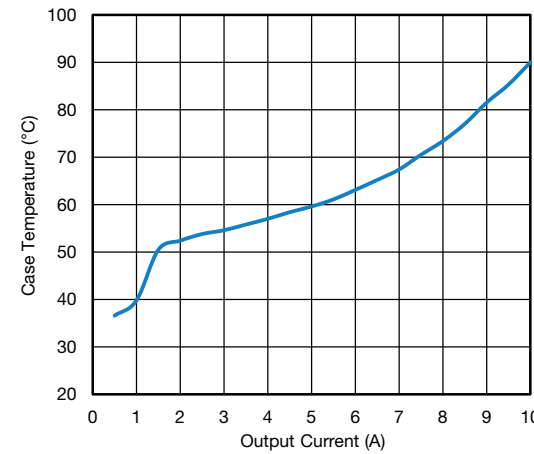


Fig. 16 - SiC461 Load Current vs. Case Temperature, VIN = 48 V, VOUT = 12 V



ELECTRICAL CHARACTERISTICS ($V_{IN} = 48\text{ V}$, $V_{OUT} = 5\text{ V}$, $f_{sw} = 300\text{ kHz}$, SiC462 (6 A), unless otherwise noted)

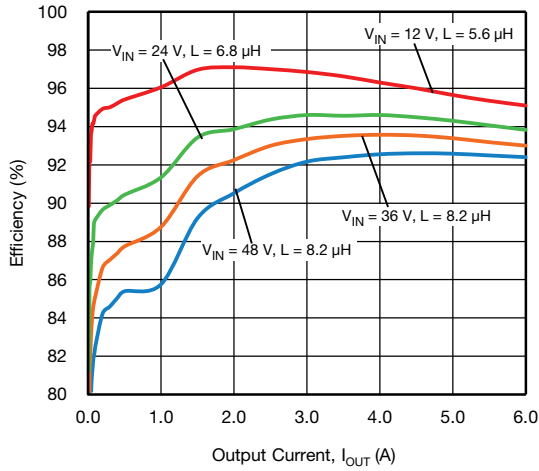


Fig. 17 - SiC462 Efficiency vs. Output Current, $V_{OUT} = 5\text{ V}$

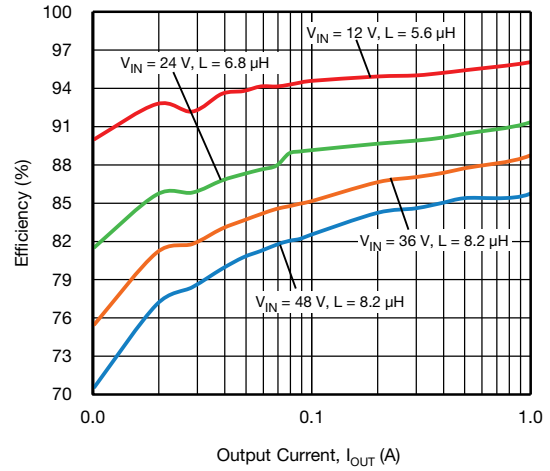


Fig. 20 - SiC462 Efficiency vs. Output Current - Light Load, $V_{OUT} = 5\text{ V}$

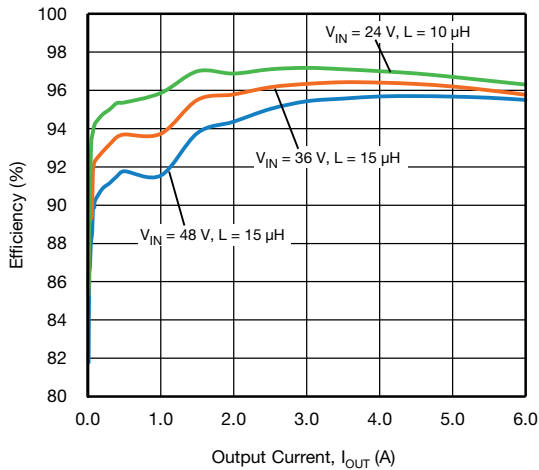


Fig. 18 - SiC462 Efficiency vs. Output Current, $V_{OUT} = 12\text{ V}$

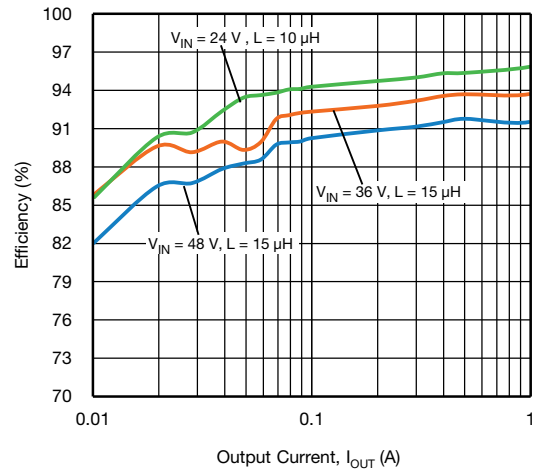


Fig. 21 - SiC462 Efficiency vs. Output Current - Light Load, $V_{OUT} = 12\text{ V}$

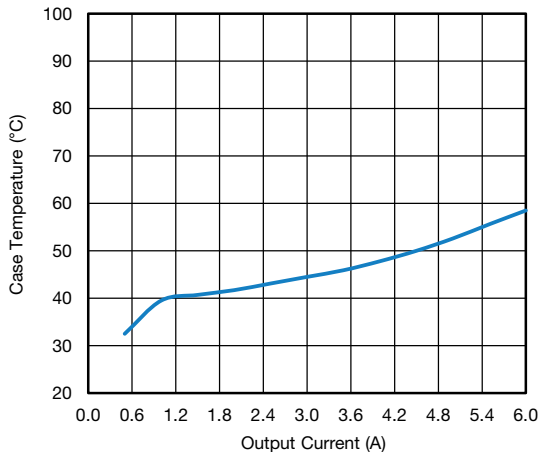


Fig. 19 - SiC462 Load Current vs. Case Temperature, $V_{IN} = 48\text{ V}$, $V_{OUT} = 5\text{ V}$

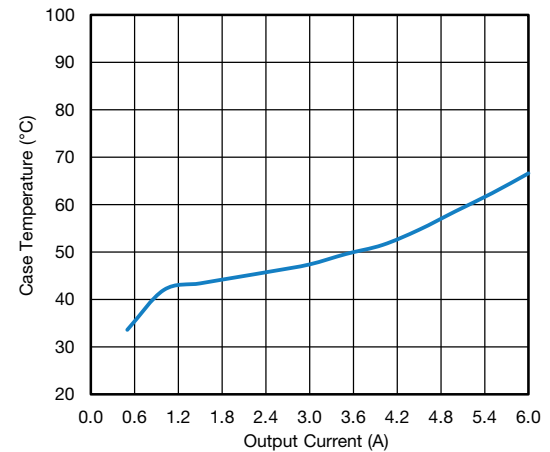


Fig. 22 - SiC462 Load Current vs. Case Temperature, $V_{IN} = 48\text{ V}$, $V_{OUT} = 12\text{ V}$



ELECTRICAL CHARACTERISTICS ($V_{IN} = 48\text{ V}$, $V_{OUT} = 5\text{ V}$, $f_{sw} = 300\text{ kHz}$, SiC463 (4 A), unless otherwise noted)

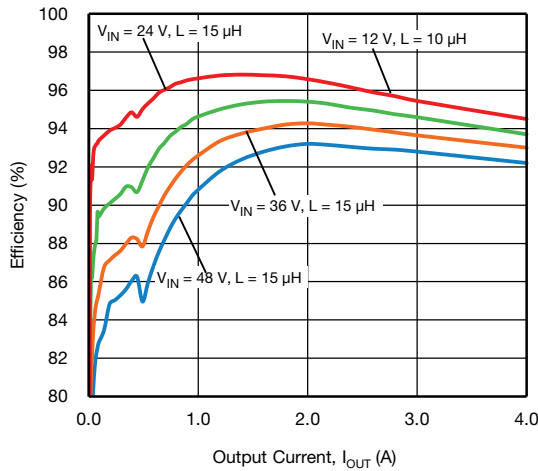


Fig. 23 - SiC463 Efficiency vs. Output Current, $V_{OUT} = 5\text{ V}$

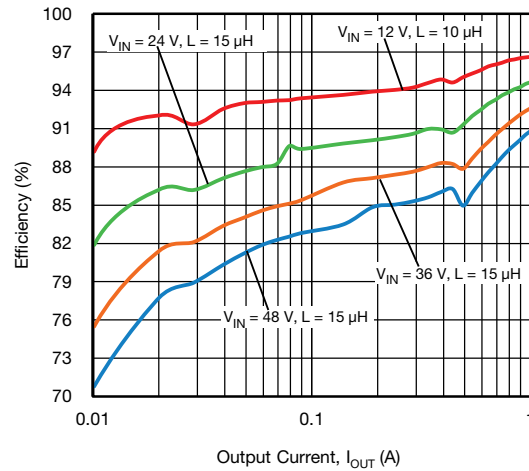


Fig. 26 - SiC463 Efficiency vs. Output Current - Light Load, $V_{OUT} = 5\text{ V}$

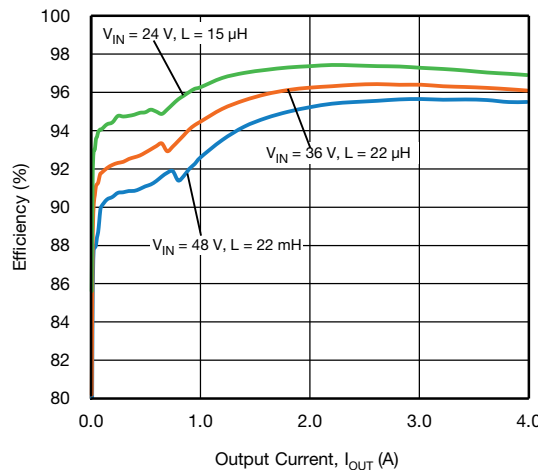


Fig. 24 - SiC463 Efficiency vs. Output Current, $V_{OUT} = 12\text{ V}$

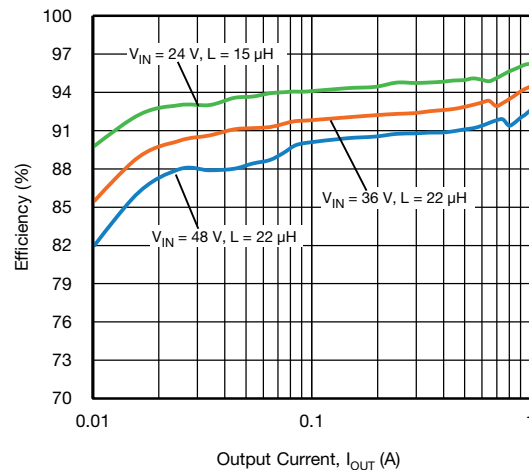


Fig. 27 - SiC463 Efficiency vs. Output Current - Light Load, $V_{OUT} = 12\text{ V}$

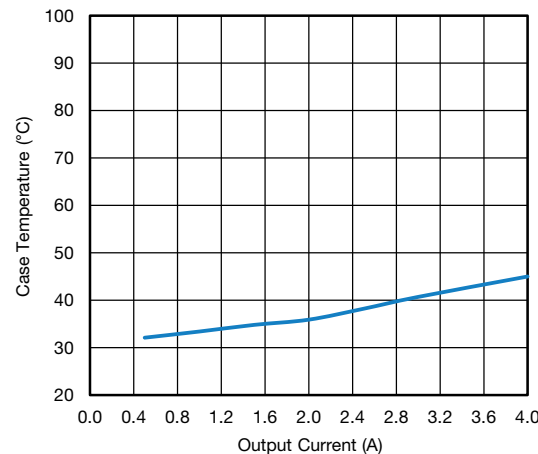


Fig. 25 - SiC463 Load Current vs. Case Temperature, $V_{IN} = 48\text{ V}$, $V_{OUT} = 5\text{ V}$

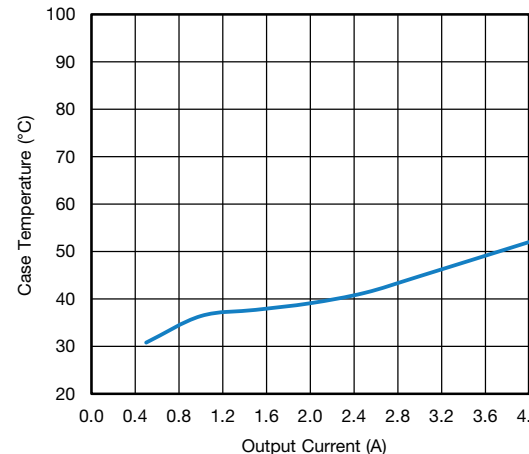


Fig. 28 - SiC463 Load Current vs. Case Temperature, $V_{IN} = 48\text{ V}$, $V_{OUT} = 12\text{ V}$



ELECTRICAL CHARACTERISTICS ($V_{IN} = 48\text{ V}$, $V_{OUT} = 5\text{ V}$, $f_{sw} = 300\text{ kHz}$, SiC464 (2 A), unless otherwise noted)

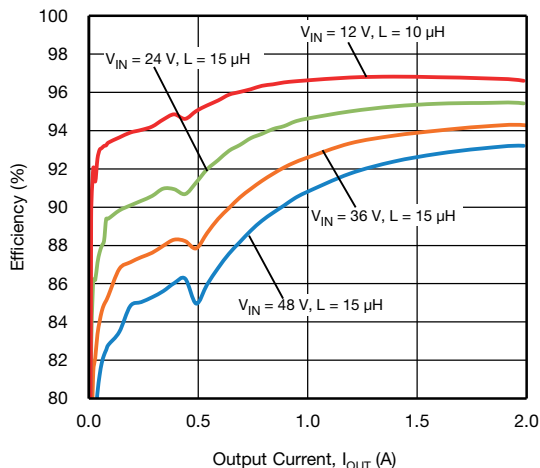


Fig. 29 - SiC464 Efficiency vs. Output Current, $V_{OUT} = 5\text{ V}$

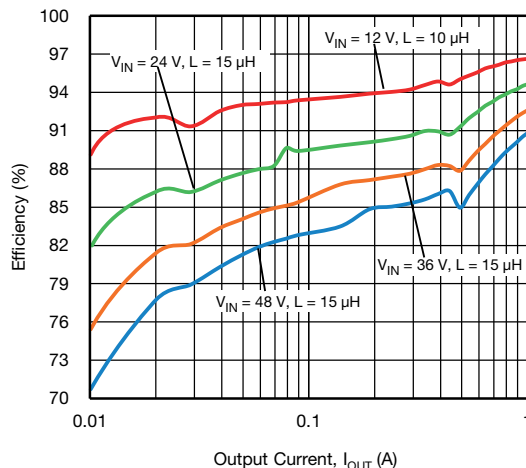


Fig. 32 - SiC464 Efficiency vs. Output Current - Light Load, $V_{OUT} = 5\text{ V}$

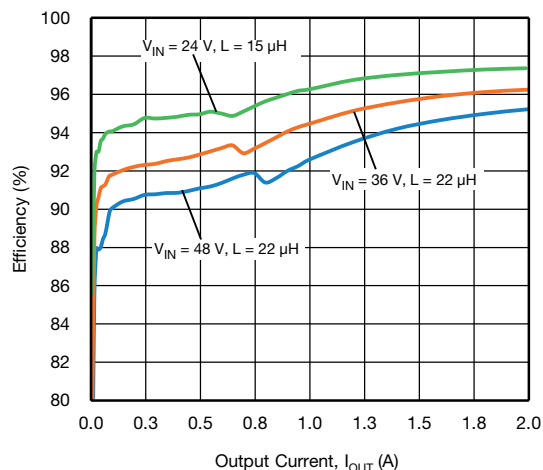


Fig. 30 - SiC464 Efficiency vs. Output Current, $V_{OUT} = 12\text{ V}$

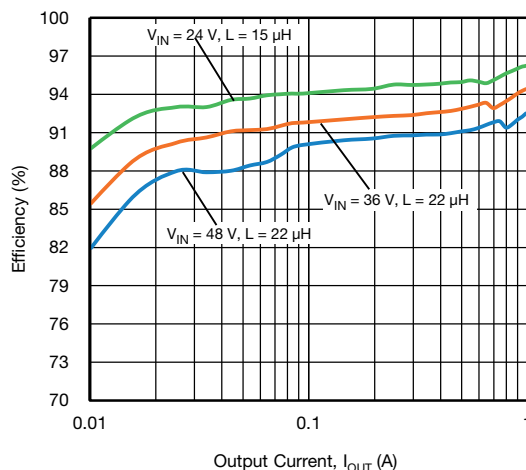


Fig. 33 - SiC464 Efficiency vs. Output Current - Light Load, $V_{OUT} = 12\text{ V}$

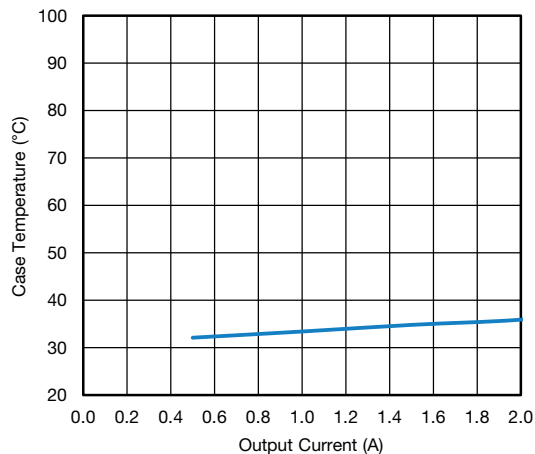


Fig. 31 - SiC464 Load Current vs. Case Temperature, $V_{IN} = 48\text{ V}$, $V_{OUT} = 5\text{ V}$

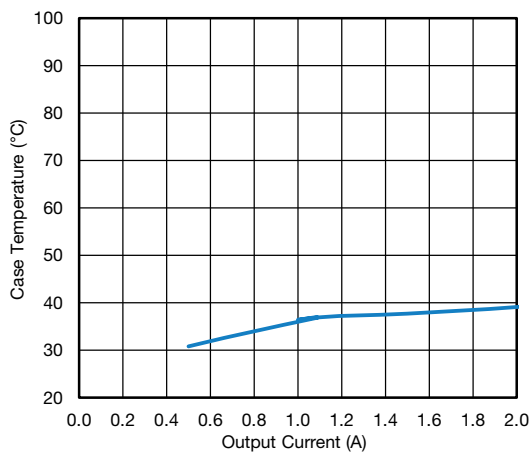


Fig. 34 - SiC464 Load Current vs. Case Temperature, $V_{IN} = 48\text{ V}$, $V_{OUT} = 12\text{ V}$



ELECTRICAL CHARACTERISTICS ($V_{IN} = 48\text{ V}$, $V_{OUT} = 5\text{ V}$, $f_{sw} = 300\text{ kHz}$, SiC462 (6 A), unless otherwise noted)

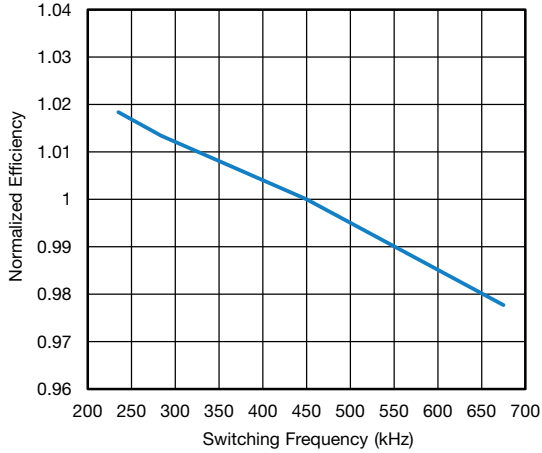


Fig. 35 - SiC461 Efficiency vs. Switching Frequency

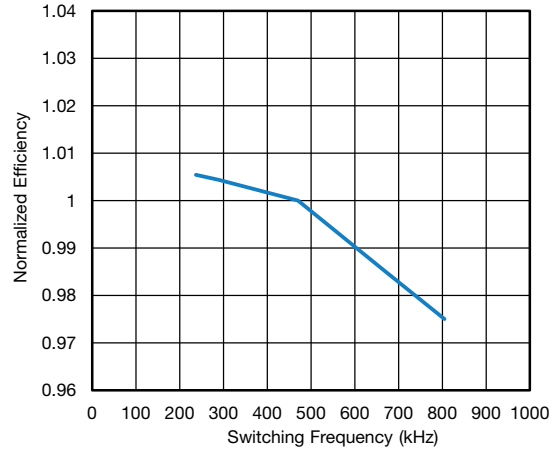


Fig. 38 - SiC462 Efficiency vs. Switching Frequency

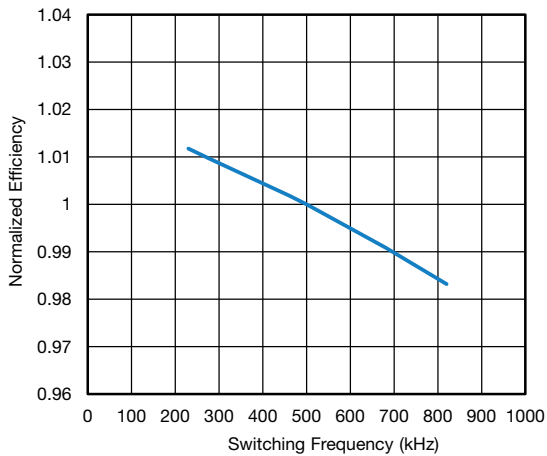


Fig. 36 - SiC463 Efficiency vs. Switching Frequency

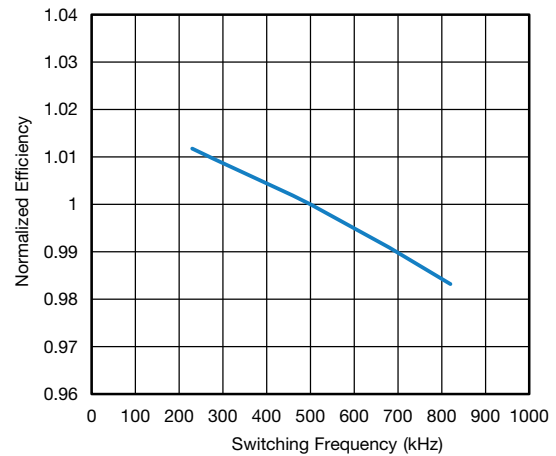


Fig. 39 - SiC464 Efficiency vs. Switching Frequency

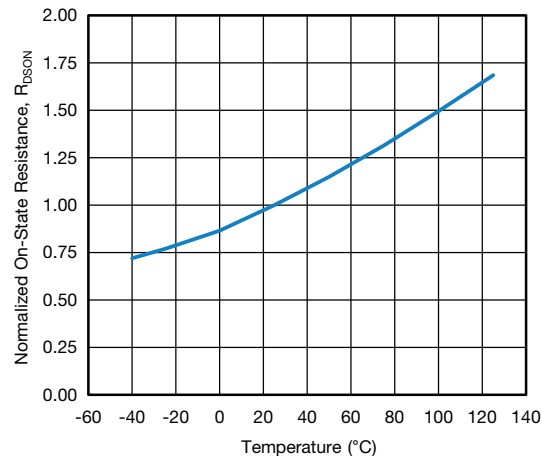


Fig. 37 - $R_{DS(ON)}$ vs. Temperature

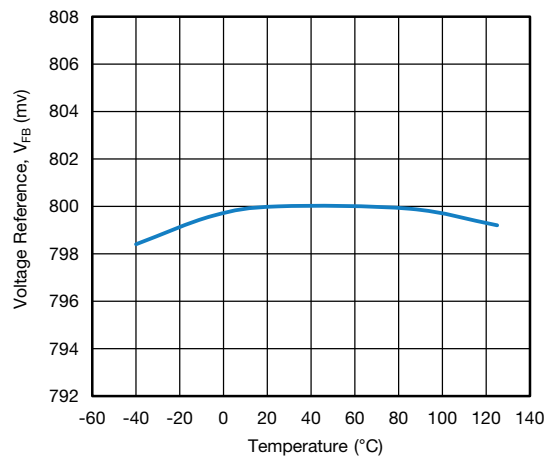


Fig. 40 - Voltage Reference vs. Temperature



ELECTRICAL CHARACTERISTICS ($V_{IN} = 48\text{ V}$, $V_{OUT} = 5\text{ V}$, $f_{sw} = 300\text{ kHz}$, SiC462 (6 A), unless otherwise noted)

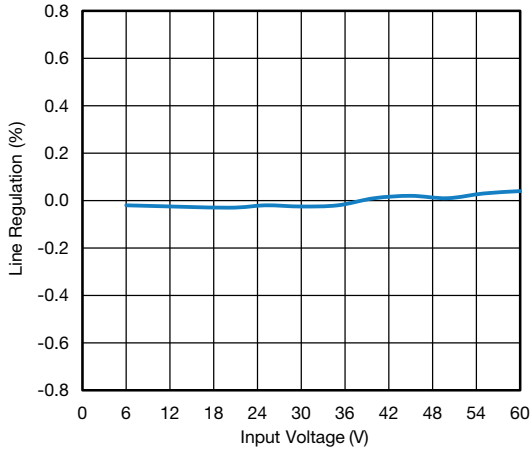


Fig. 41 - Line Regulation

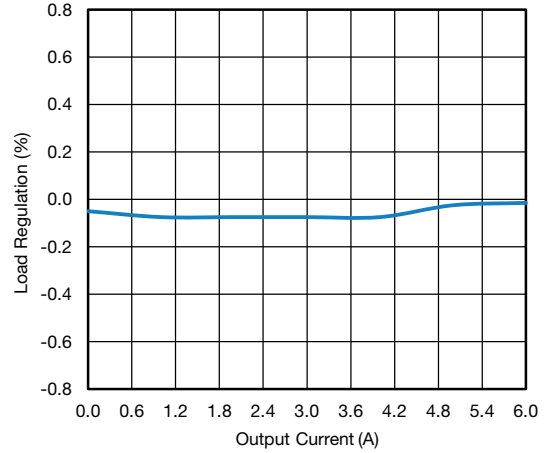


Fig. 44 - Load Regulation

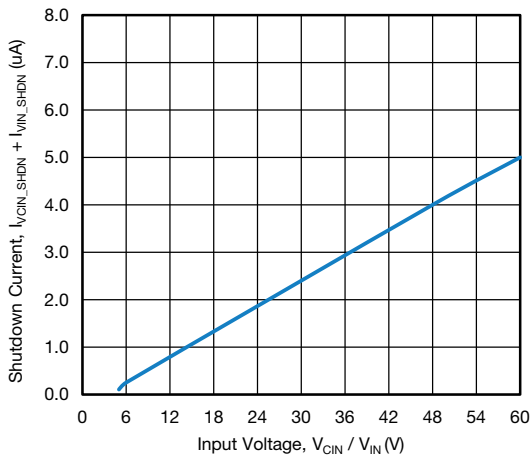


Fig. 42 - Shutdown Current vs. Input Voltage

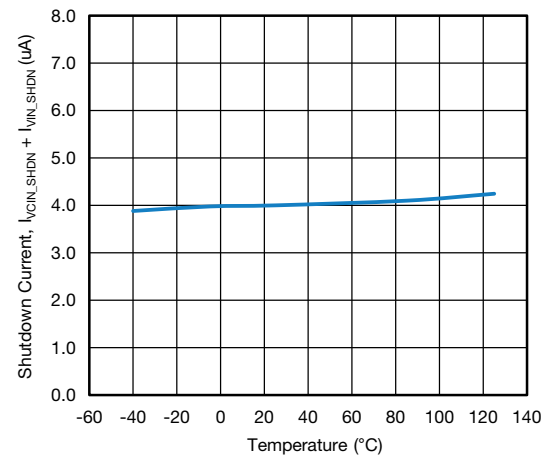


Fig. 45 - Shutdown Current vs. Junction Temperature

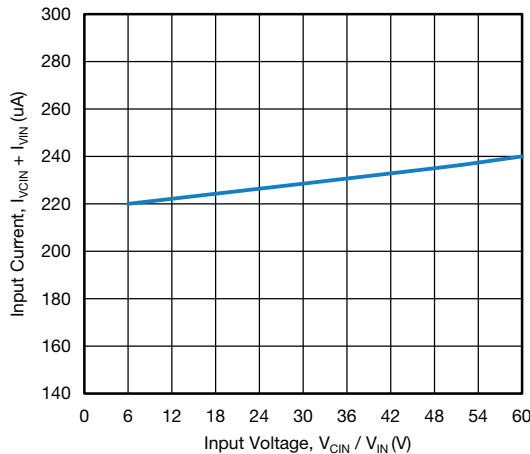


Fig. 43 - Input Current vs. Input Voltage

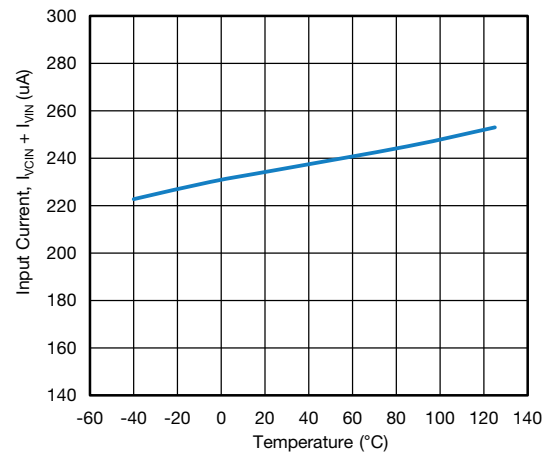


Fig. 46 - Input Current vs. Junction Temperature

ELECTRICAL CHARACTERISTICS ($V_{IN} = 48\text{ V}$, $V_{OUT} = 5\text{ V}$, $f_{sw} = 300\text{ kHz}$, SiC462 (6 A), unless otherwise noted)

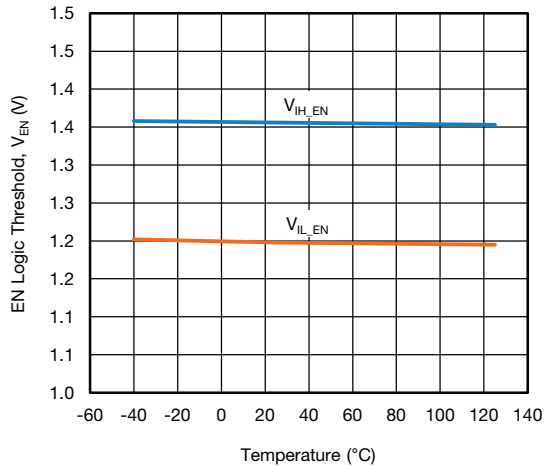


Fig. 47 - EN Logic Threshold vs. Junction Temperature

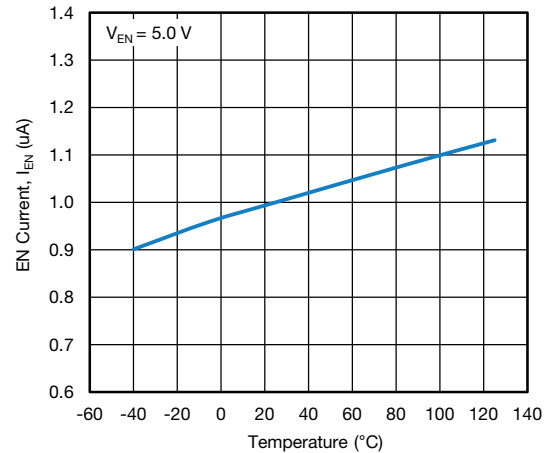


Fig. 50 - EN Current vs. Junction Temperature

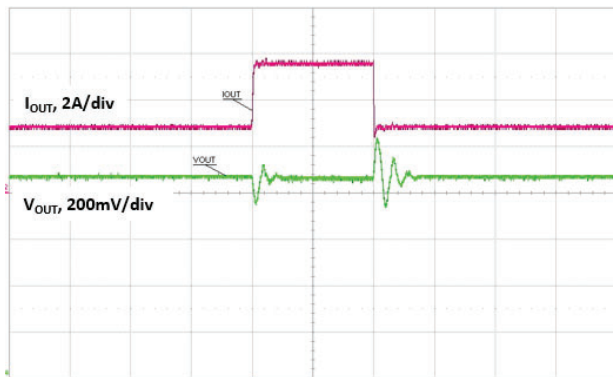


Fig. 48 - Load Transient (3 A to 6 A), Time = 100 μ s/div

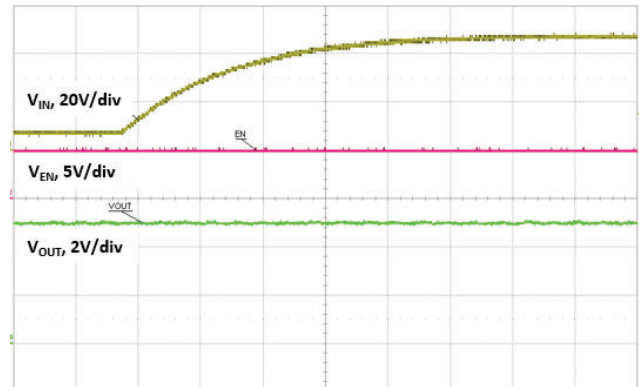


Fig. 51 - Line Transient (8 V to 48 V), Time = 10 ms/div

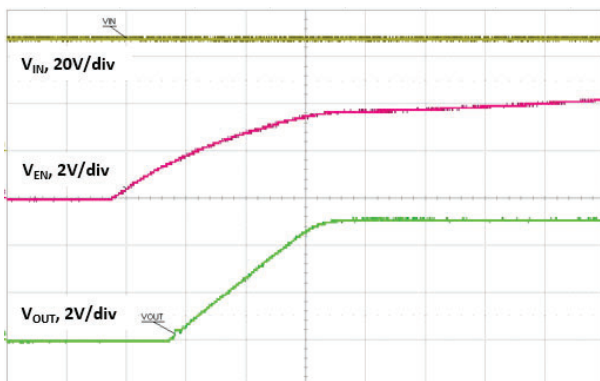


Fig. 49 - Start-Up with EN, Time = 1 ms/div

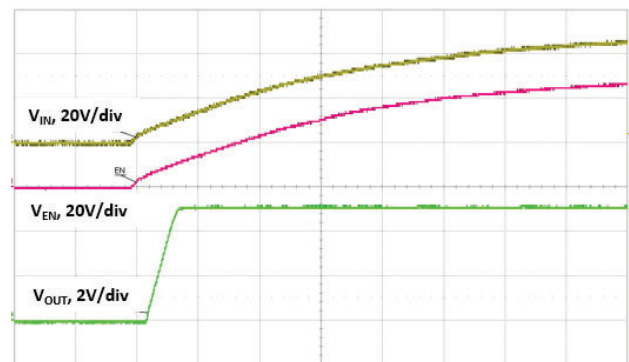


Fig. 52 - Start-up with V_{IN} , Time = 5 ms/div

ELECTRICAL CHARACTERISTICS ($V_{IN} = 48\text{ V}$, $V_{OUT} = 5\text{ V}$, $f_{sw} = 300\text{ kHz}$, SiC462 (6 A), unless otherwise noted)

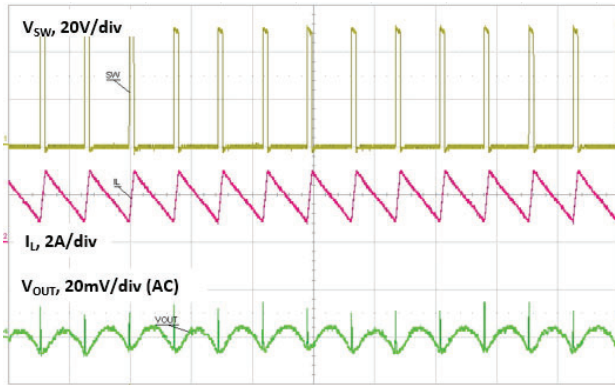


Fig. 53 - Output Ripple 2 A, Time = 5 μ s/div

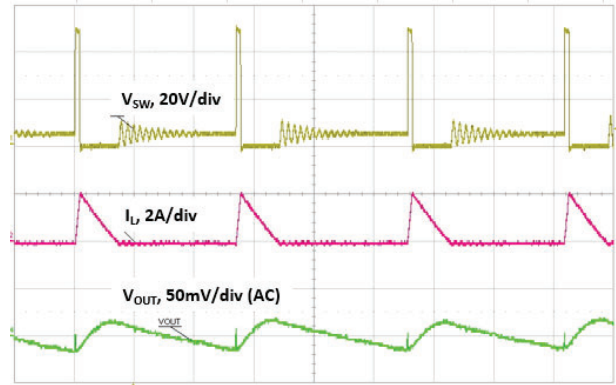


Fig. 55 - Output Ripple 300 mA, Time = 5 μ s/div

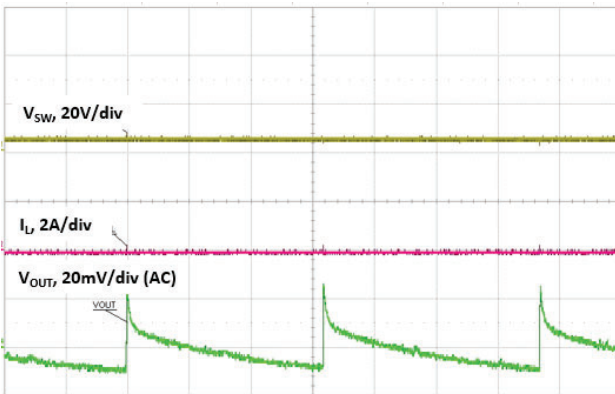


Fig. 54 - Output Ripple PSM, Time = 10 ms/div

PCB LAYOUT RECOMMENDATIONS

Step 1: V_{IN} /GND Planes and Decoupling

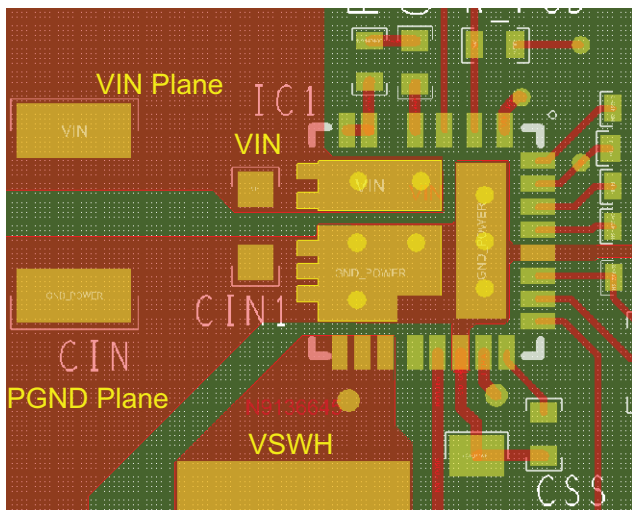


Fig. 56

1. Layout V_{IN} and P_{GND} planes as shown above
2. Ceramic capacitors should be placed between V_{IN} and P_{GND} , and very close to the device for best decoupling effect
3. Various ceramic capacitor values and package sizes should be used to cover entire coupling spectrum e.g. 1210 and 0603
4. Smaller capacitance values, closer to V_{IN} pin(s), provide better high frequency response

Step 2: V_{CIN} Pin

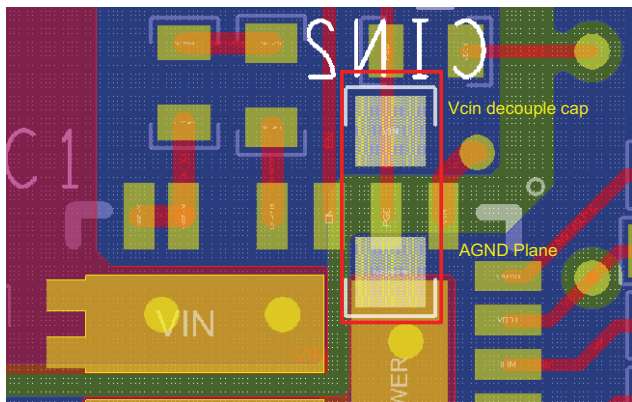


Fig. 57

1. V_{CIN} is the input pin for both internal LDO and t_{ON} block. t_{ON} varies with input voltage and it is necessary to put a decoupling capacitor close to this pin
2. The connection can be made through a via and the capacitor can be placed at bottom layer

Step 3: SW Plane

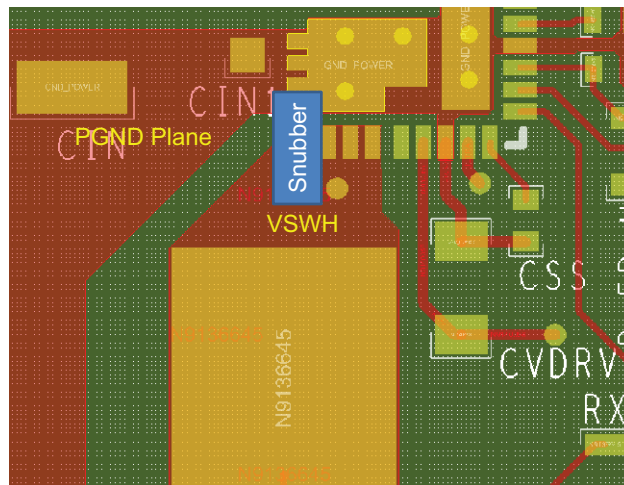


Fig. 58

1. Connect output inductor to device with large plane to lower resistance
2. If any snubber network is required, place the components on the bottom side as shown above

Step 4: V_{DD}/V_{DRV} Input Filter

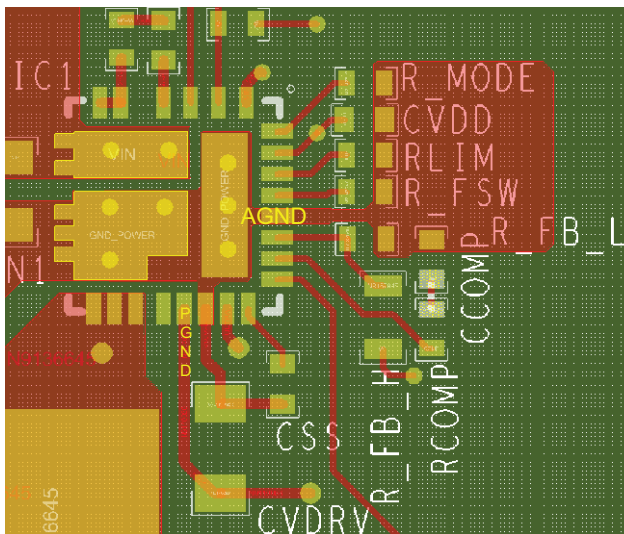
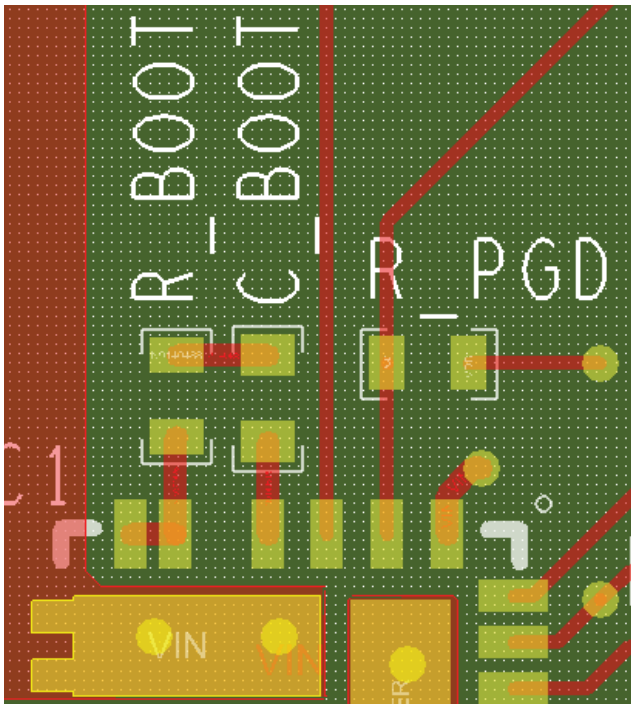
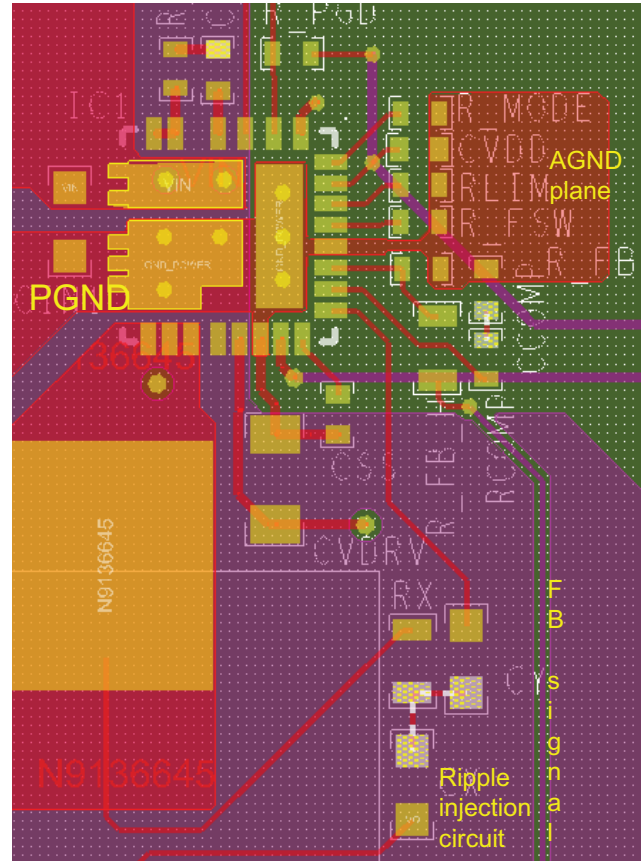


Fig. 59

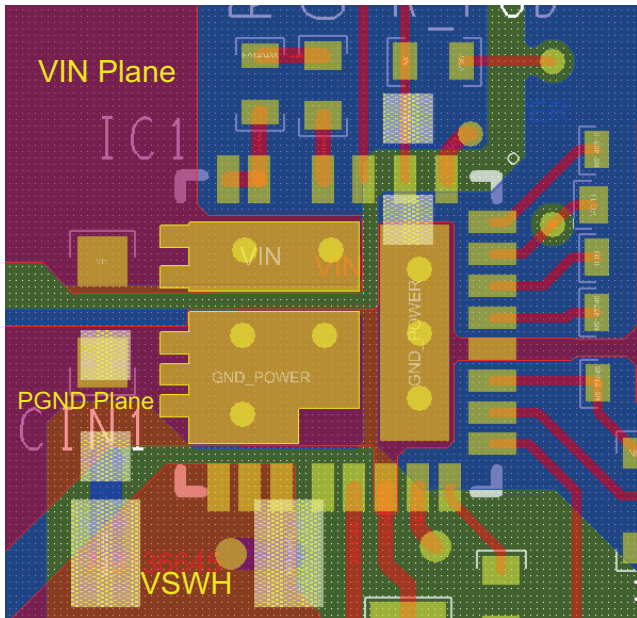
1. C_{VDD} cap should be placed between V_{DD} and A_{GND} to achieve best noise filtering
2. C_{VDRV} cap should be placed close to V_{DRV} and P_{GND} pins to reduce effects of trace impedance and provide maximum instantaneous driver current for low side MOSFET during switching cycle

Step 5: BOOT Resistor and Capacitor Placement

Fig. 60

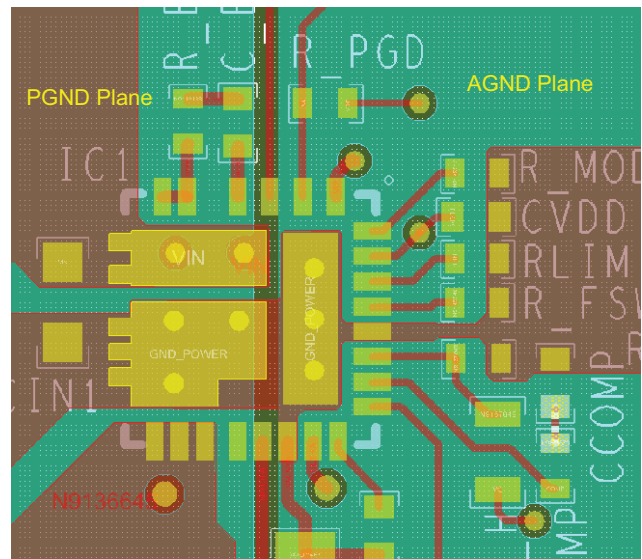
1. C_{BOOT} and R_{BOOT} need to be placed very close to the device, between PHASE and BOOT pins
2. In order to reduce parasitic inductance, it is recommended to use 0402 chip size for the resistor and the capacitor

Step 6: Signal Routing

Fig. 61

1. Separate the small analog signal from high current path. As shown above, the high current paths with high dv/dt , di/dt are placed on the left side of the IC, while the small control signals are placed on the right side of the IC. All the components for small analog signal should be placed closer to IC with minimum trace length
2. IC analog ground (A_{GND}), pin 23, should have a single connection to P_{GND} . The A_{GND} ground plane connected to pin 23 helps to keep A_{GND} quiet and improves noise immunity
3. Feedback signal can be routed through inner layer. Make sure this signal is far from SW node and shielded by inner ground layer
4. Ripple injection circuit can be placed next to inductor. Kelvin connection as shown above is recommended

Step 7: Adding Thermal Relief Vias and Duplicate Power Path Plane

Fig. 62

1. Thermal relief vias can be added on the V_{IN} and P_{GND} pads to utilize inner layers for high current and thermal dissipation
2. To achieve better thermal performance, additional vias can be placed on V_{IN} and P_{GND} planes. It is also necessary to duplicate the V_{IN} and ground plane at bottom layer to maximize the power dissipation capability of the PCB
3. SW pad is a noise source and it is not recommended to place vias on this pad
4. 8 mil vias on pads and 10 mil vias on planes are ideal via sizes. The vias on pad may drain solder during assembly and cause assembly issues. Please consult with the assembly house for guideline

Step 8: Ground Layer

Fig. 63

1. It is recommended to make the entire inner layer (next to top layer) ground plane
2. This ground plane provides shielding between noise source on top layer and signal trace within inner layer
3. The ground plane can be broken into two sections, P_{GND} and A_{GND}

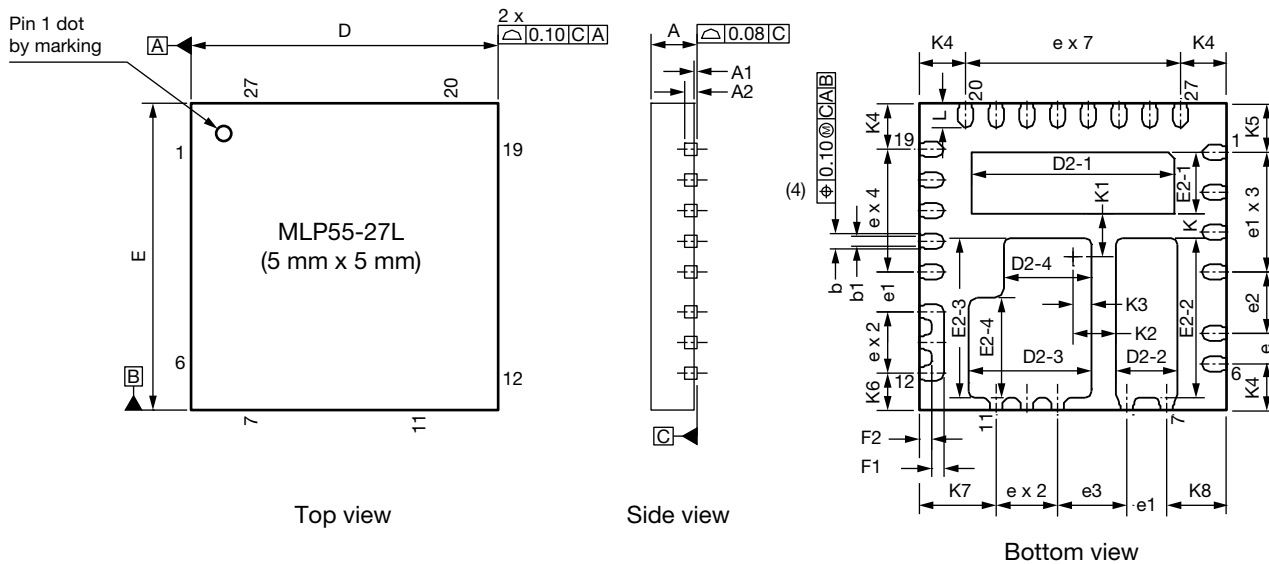


| PRODUCT SUMMARY | | | | |
|-------------------------------|---|--|--|--|
| Part number | SiC461 | SiC462 | SiC463 | SiC464 |
| Description | 10 A, 4.5 V to 60 V input, 100 kHz to 2 MHz, synchronous buck regulator | 6 A, 4.5 V to 60 V input, 100 kHz to 2 MHz, synchronous buck regulator | 4 A, 4.5 V to 60 V input, 100 kHz to 2 MHz, synchronous buck regulator | 2 A, 4.5 V to 60 V input, 100 kHz to 2 MHz, synchronous buck regulator |
| Input voltage min. (V) | 4.5 | 4.5 | 4.5 | 4.5 |
| Input voltage max. (V) | 60 | 60 | 60 | 60 |
| Output voltage min. (V) | 0.8 | 0.8 | 0.8 | 0.8 |
| Output voltage max. (V) | $0.92 \times V_{IN}$ | $0.92 \times V_{IN}$ | $0.92 \times V_{IN}$ | $0.92 \times V_{IN}$ |
| Continuous current (A) | 10 | 6 | 4 | 2 |
| Switch frequency min. (kHz) | 100 | 100 | 100 | 100 |
| Switch frequency max. (kHz) | 2000 | 2000 | 2000 | 2000 |
| Pre-bias operation (yes / no) | Yes | Yes | Yes | Yes |
| Internal bias reg. (yes / no) | Yes | Yes | Yes | Yes |
| Compensation | External | External | External | External |
| Enable (yes / no) | Yes | Yes | Yes | Yes |
| P _{GOOD} (yes / no) | Yes | Yes | Yes | Yes |
| Overcurrent protection | Yes | Yes | Yes | Yes |
| Protection | OVP, OCP, UVP/SCP, OTP, UVLO | OVP, OCP, UVP/SCP, OTP, UVLO | OVP, OCP, UVP/SCP, OTP, UVLO | OVP, OCP, UVP/SCP, OTP, UVLO |
| Light load mode | Selectable powersave / ultrasonic | Selectable powersave / ultrasonic | Selectable powersave / ultrasonic | Selectable powersave / ultrasonic |
| Peak efficiency (%) | 98 | 98 | 98 | 98 |
| Package type | PowerPAK MLP55-27L | PowerPAK MLP55-27L | PowerPAK MLP55-27L | PowerPAK MLP55-27L |
| Package size (W, L, H) (mm) | 5 x 5 x 0.75 | 5 x 5 x 0.75 | 5 x 5 x 0.75 | 5 x 5 x 0.75 |
| Status code | 1 | 1 | 1 | 1 |
| Product type | microBUCK (step down regulator) | microBUCK (step down regulator) | microBUCK (step down regulator) | microBUCK (step down regulator) |
| Applications | Computing, consumer, industrial, healthcare, networking | Computing, consumer, industrial, healthcare, networking | Computing, consumer, industrial, healthcare, networking | Computing, consumer, industrial, healthcare, networking |

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PowerPAK® MLP55-27 Case Outline



| DIM. | MILLIMETERS | | | INCHES | | |
|------------------|-------------|------|------|------------|-------|-------|
| | MIN. | NOM. | MAX. | MIN. | NOM. | MAX. |
| A ⁽⁸⁾ | 0.70 | 0.75 | 0.80 | 0.027 | 0.029 | 0.031 |
| A1 | 0.00 | - | 0.05 | 0.000 | - | 0.002 |
| A2 | 0.20 ref. | | | 0.008 ref. | | |
| b ⁽⁴⁾ | 0.20 | 0.25 | 0.30 | 0.008 | 0.010 | 0.012 |
| b1 | 0.15 | 0.20 | 0.25 | 0.006 | 0.008 | 0.010 |
| D | 5.00 BSC | | | 0.197 BSC | | |
| e | 0.50 BSC | | | 0.020 BSC | | |
| e1 | 0.65 BSC | | | 0.026 BSC | | |
| e2 | 1.00 BSC | | | 0.039 BSC | | |
| e3 | 1.13 BSC | | | 0.044 BSC | | |
| E | 5.00 BSC | | | 0.197 BSC | | |
| L | 0.35 | 0.40 | 0.45 | 0.014 | 0.016 | 0.018 |
| N ⁽³⁾ | 28 | | | 28 | | |
| D2-1 | 3.25 | 3.30 | 3.35 | 0.128 | 0.130 | 0.132 |
| D2-2 | 0.95 | 1.00 | 1.05 | 0.037 | 0.039 | 0.041 |
| D2-3 | 1.95 | 2.00 | 2.05 | 0.077 | 0.079 | 0.081 |
| D2-4 | 1.37 | 1.42 | 1.47 | 0.054 | 0.056 | 0.058 |
| E2-1 | 0.95 | 1.00 | 1.05 | 0.037 | 0.039 | 0.041 |
| E2-2 | 2.55 | 2.60 | 2.65 | 0.100 | 0.102 | 0.104 |
| E2-3 | 2.55 | 2.60 | 2.65 | 0.100 | 0.102 | 0.104 |
| E2-4 | 1.58 | 1.63 | 1.68 | 0.062 | 0.064 | 0.066 |
| F1 | 0.20 | - | 0.25 | 0.008 | - | 0.010 |
| F2 | min. 0.20 | | | min. 0.008 | | |

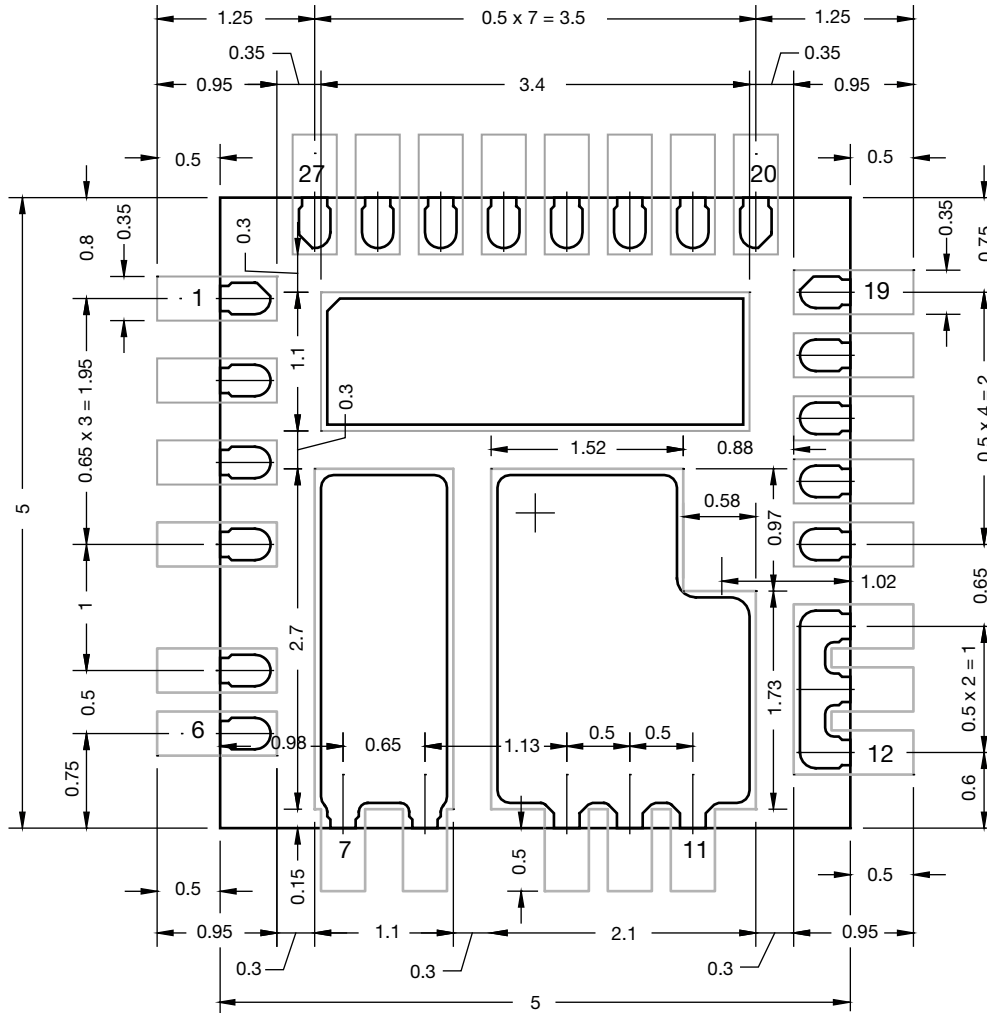


| DIM. | MILLIMETERS | | | INCHES | | |
|--|-------------|------|------|------------|------|------|
| | MIN. | NOM. | MAX. | MIN. | NOM. | MAX. |
| K | 0.40 BSC | | | 0.016 BSC | | |
| K1 | 0.70 BSC | | | 0.028 BSC | | |
| K2 | 0.70 BSC | | | 0.028 BSC | | |
| K3 | 0.30 BSC | | | 0.012 BSC | | |
| K4 | 0.75 BSC | | | 0.030 BSC | | |
| K5 | 0.80 BSC | | | 0.0315 BSC | | |
| K6 | 0.60 BSC | | | 0.024 BSC | | |
| K7 | 1.25 BSC | | | 0.049 BSC | | |
| K8 | 0.975 BSC | | | 0.038 BSC | | |
| ECN: T18-0594-Rev. C, 03-Dec-2018 DWG: 6056 | | | | | | |

Notes

- (1) Use millimeters as the primary measurement
- (2) Dimensioning and tolerances conform to ASME Y14.5M. - 1994
- (3) N is the number of terminals
Nd is the number of terminals in x-direction
Ne is the number of terminals in y-direction
- (4) Dimension b applies to plated terminal and is measured between 0.20 mm and 0.25 mm from terminal tip
- (5) The pin #1 identifier must be existed on the top surface of the package by using indentation mark or other feature of package body
- (6) Exact shape and size of this feature is optional
- (7) Package warpage max. 0.08 mm
- (8) Applied only for terminals

Recommended Land Pattern PowerPAK® MLP55-27L



All dimensions in millimeters



Component for MLP55-27L



Land pattern for MLP55-27L



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